

## Introduction

Underwater laser links offer high bandwidth, low latency, and phase-sensitive modulation for applications such as autonomous vehicles, sensor networks, and secure naval communications; their performance is governed by the water’s optical properties: **absorption**, **scattering**, and overall **turbidity**.

In this work we analyze same-depth point-to-point links while ignoring turbulence, model attenuation with the Beer–Lambert law  $T(d, \lambda) = \exp(-K_d(\lambda) d)$ , and use Jerlov water-type diffuse attenuation coefficients  $K_d(\lambda)$  to provide a physically grounded baseline for channel transmittance applicable to communication and Continuous-Variable Quantum Key Distribution performance estimates(CV<sub>Q</sub>KD).

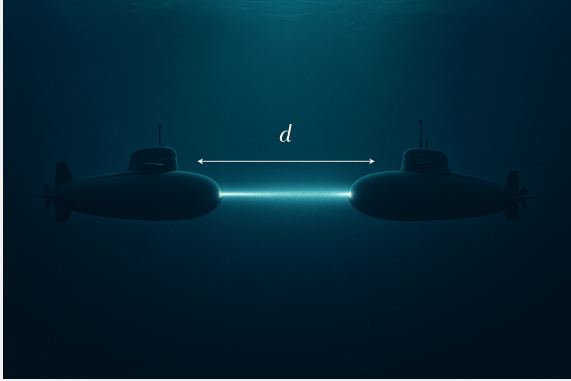


Figure 1. Schematic: Two submarines communicating at the same depth (same-depth communication).

## Objectives

- **Objective A:** Model turbidity-induced variability around the Beer–Lambert baseline using a Monte-Carlo PDF approach and explore dependence on distance and heterogeneity (cells/m).
- **Objective B:** Provide plots of deterministic Beer–Lambert transmittance and stochastic Probability Distribution Function (PDF) of normalized received intensity  $I/I_0$  across wavelengths 450–550 nm for representative Jerlov types.

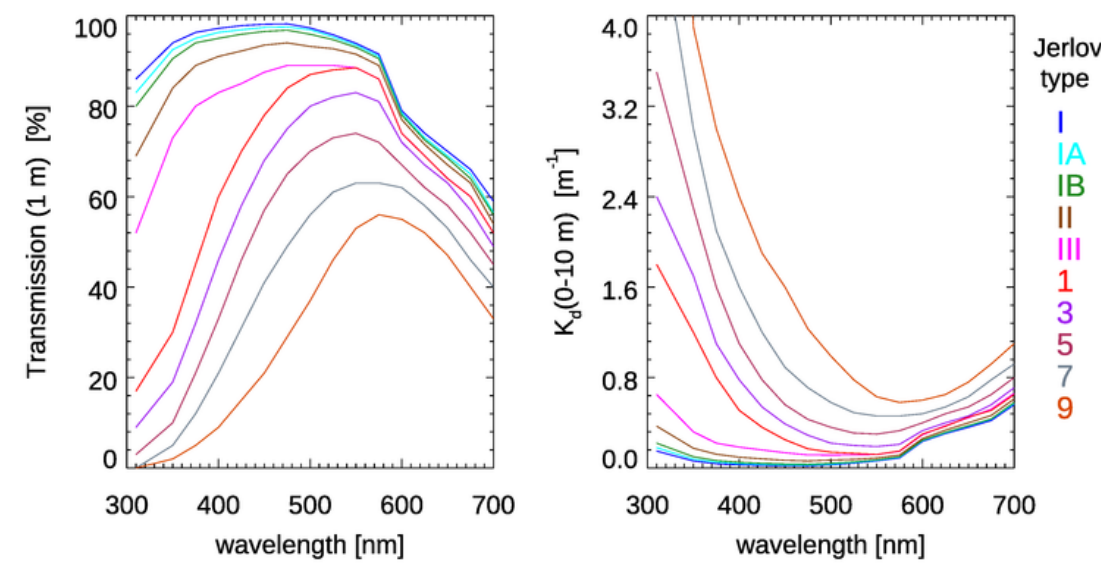


Figure 2. Jerlov  $K_d$  values. (DataSource : Jerlov, 1976)

## Background

- *Jerlov water classification:* Jerlov grouped natural waters by optical clarity (oceanic types I, IA, IB, II, III and coastal types 1–9). Each type is associated with characteristic spectral attenuation behavior; we use representative  $K_d(\lambda)$  values for these types as the attenuation coefficients in the Beer–Lambert law.
- *Beer–Lambert law (same-depth):* For a path length  $d$  and wavelength  $\lambda$ ,  $I(d, \lambda) = I_0 \exp(-K_d(\lambda) d)$ , and the deterministic channel transmittance is

$$T_c(d, \lambda) = \frac{P_{\text{received}}}{P_{\text{transmitted}}} = \exp(-K_d(\lambda) d).$$

- *Absorption vs. scattering:* Particle composition controls whether attenuation is absorption-dominated (e.g., algal/phytoplankton increases  $\mu_a$ ) or scattering-dominated (e.g., mineral particles, CDOM increase  $\mu_s$ ). Both contribute to  $K_d$  but affect beam coherence differently.
- *Turbidity and heterogeneity:* Turbidity is the macroscopic manifestation of suspended particles and dissolved matter; small-scale heterogeneity can be represented statistically as fluctuations around the Beer–Lambert mean.

## Method ( Beer–Lambert baseline)

### Assumptions.

- Same-depth geometry (transmitter and receiver at equal depth).
- Turbulence effects are ignored.
- Total attenuation described by Jerlov diffuse attenuation coefficient  $K_d(\lambda)$ .

**Deterministic transmittance.** For each Jerlov type and wavelength  $\lambda$  we compute  $T_c(d, \lambda) = \exp(-K_d(\lambda) d)$ ,

over a range of distances  $d$  (meters). These curves form the baseline channel loss used in communication and cryptographic performance calculations.

**Stochastic turbidity model .** To represent small-scale turbidity variability we model the normalized received intensity

$$X = \frac{I}{I_0}$$

as a Gaussian random variable with mean  $\mu = \exp(-K_d d)$  and standard deviation  $\sigma = \eta(\text{cells/m}) \cdot \mu$ . The PDF is

$$\text{PDF}(X) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(X - \mu)^2}{2\sigma^2}\right),$$

truncated to  $X \in [0, 1]$ . The parameter cells/m is a tunable proxy for heterogeneity;  $\eta$  is a small scaling factor (e.g., 0.05–0.2). This approach reproduces PDF plots of normalized intensity while keeping the Beer–Lambert mean explicit.

**Wavelength sampling.** We evaluate  $\lambda$  in the blue–green window (450–550 nm) with 20 nm intervals to capture the spectral window of maximum penetration.

**Outputs.** For each Jerlov type and wavelength we produce:

- Beer–Lambert transmittance vs distance plots.
- Monte-Carlo simulation is used to observe normalized intensity  $I/I_0$  for selected distances and cells/m values.
- Summary tables of mean transmittance vs distance.

## Numerical implementation

We implement the model in Mathematica. Key steps:

1. Load representative Jerlov  $K_d(\lambda)$  values (or use published tables).
2. For each  $\lambda$  and Jerlov type compute deterministic  $T_c(d, \lambda)$ .
3. Sample  $N$  realizations of  $X \sim \mathcal{N}(\mu, \sigma^2)$  with  $\mu = \exp(-K_d d)$  and  $\sigma = \eta\mu$ ; clip to  $[0, 1]$ .
4. Plot histograms (PDF) and overlay fitted Gaussian curve; repeat across distances and cells/m.

## Results (expected / example panels)

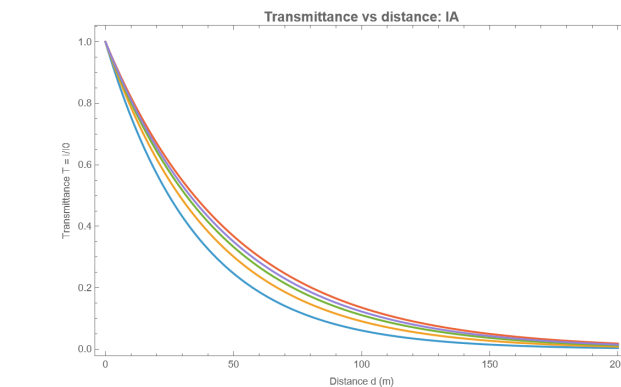


Figure 3. Distance vs Transmittance across different wavelength using Monte-Carlo simulation

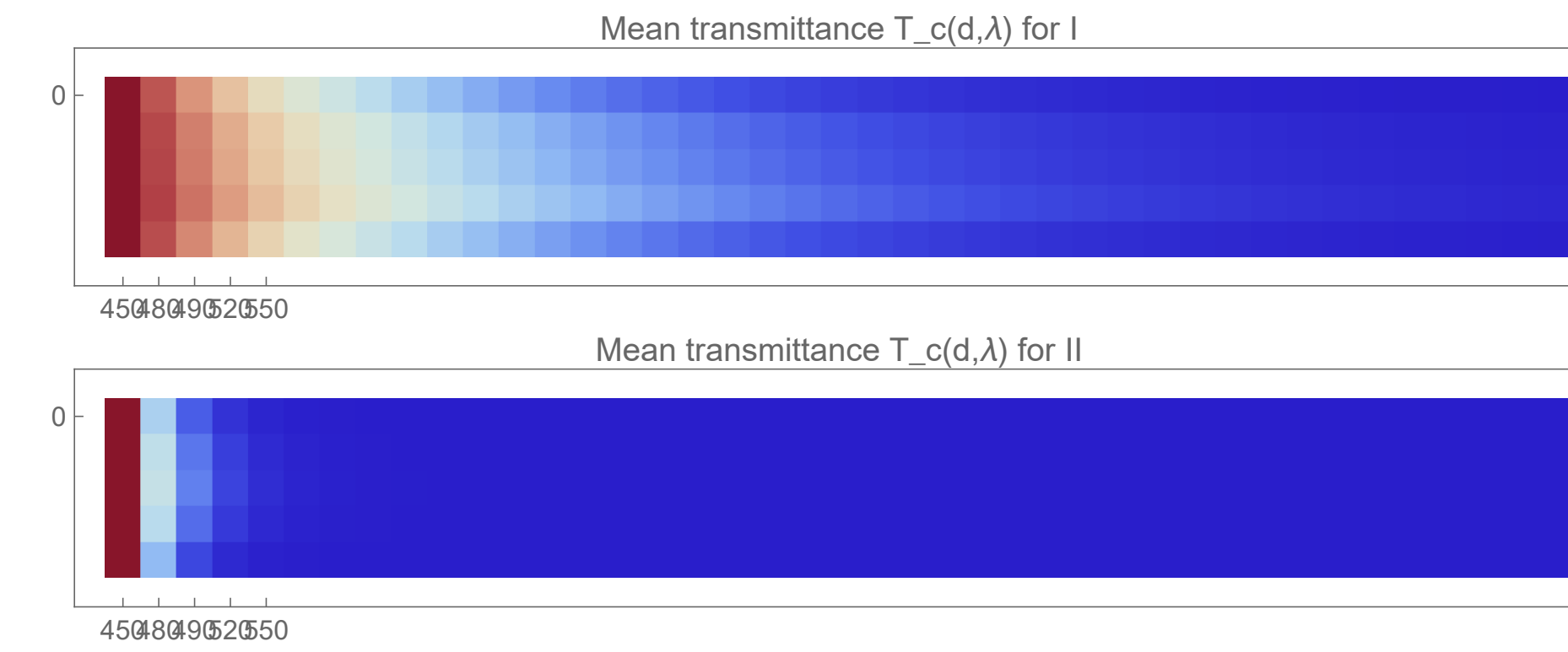


Figure 4. Heat maps for different Jerlov Water types

- **Panel 1:** Beer–Lambert transmittance vs distance for Jerlov types I, II, III at  $\lambda = 480$  and  $520$  nm. Clear waters (Type I) show slow decay; turbid waters (Type III) decay rapidly.
- **Panel 3:** Summary heatmap of mean transmittance  $T_c(d, \lambda)$  vs distance and wavelength for selected Jerlov types.

The deterministic Beer–Lambert baseline provides a direct mapping from Jerlov type to expected channel loss.

## Discussion and Future work

- The Beer–Lambert + Jerlov approach yields a simple, physically grounded baseline for channel transmittance in same-depth links and is directly usable in CV-QKD key-rate calculations (channel transmittance  $T_c$  and excess noise estimates).
- Future work: Consider using a model and that differently treats absorption and scattering coefficients; incorporate ABCD turbulence cells for beam-shape effects.

## Acknowledgements

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