

# Introduction to convex sets

A. Guevara

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## 1 Basic concepts

- Affine sets
- Convex sets
- Cones

## 2 Some relationships between the basic concepts

- Affine hull and convex hull
- Affine hull and convex cone
- Convex sets and convex cone
- Caratheodory's Theorem

# References

- Bertsekas, D.P., Nedić, A. and Ozdaglar, A. *Convex analysis and optimization*. Athena Scientific, Belmont, Massachusetts, 2003.
- Borwein, J.M. and Lewis, A.S. *Convex analysis and nonlinear optimization*. Springer Verlag, N.Y., 2000.
- Boyd, S. and Vanderberghe, L. *Convex optimization*. Cambridge Univ. Press, Cambridge, U.K., 2004.
- Rockafellar, R.T. *Convex analysis*. Princeton Univ. Press, Princeton, N.J., 1970.

# Notation

- We work in a  $n$ -dimensional real Euclidean space  $E$ .
- Sets will be indicated with capital letters.
- Points and vectors will be lower case.
- For scalars we use greek characters.

# Definition

- $M \subset E$  is affine if for any two points  $x$  and  $y$  in  $M$ , the line passing through  $x$  and  $y$  is contained in  $M$ .

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  - (a)  $\emptyset$ ,  $E$ , singletons
  - (b) Subspaces
  - (c) Hyperplanes

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  - (b) Subspaces
  - (c) Hyperplanes
- General form

$$M = a + L,$$

$a \in M$ ,  $L$  subspace

$$\dim(M) = \dim(L)$$

# Affine hull

For  $S \subset E$ ,

$$\begin{aligned} \text{aff}(S) &= \text{smallest affine set containing } S \\ &= \left\{ \sum_{i=1}^m \lambda_i x_i \mid x_i \in S, \sum_{i=1}^m \lambda_i = 1, m \in \mathbb{N} \right\} \end{aligned}$$

We define

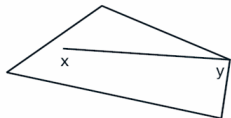
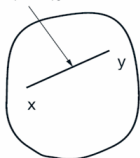
$$\dim(S) = \dim \text{aff}(S)$$



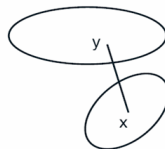
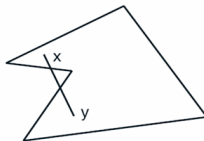
# Definition

$C \subset E$  is convex if for any two points  $x$  and  $y$  in  $C$ , the *line segment* passing through  $x$  and  $y$  is contained in  $C$ .

$$\alpha x + (1 - \alpha)y, 0 < \alpha < 1$$



Convex Sets



Nonconvex Sets

# Properties

## Set operations that preserve convexity

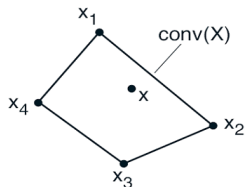
- Arbitrary intersections.
- Scalar multiplication.
- Vector sum.
- Image and inverse image under linear and affine transformations.

# Convex hull

For  $X \subset E$ ,

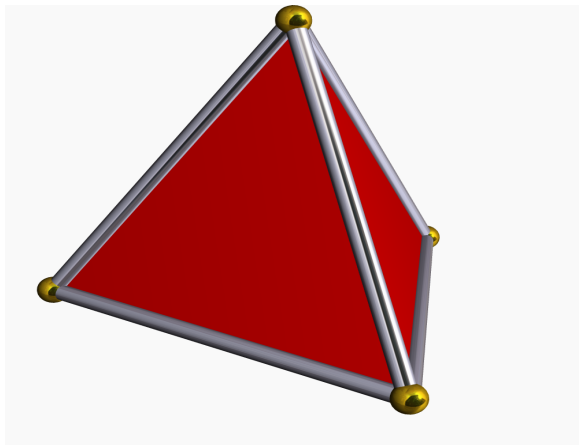
$\text{conv}(X)$  = smallest convex set containing  $X$

$$= \left\{ \sum_{i=1}^m \lambda_i x_i \mid x_i \in X, \lambda_i \geq 0, \sum_{i=1}^m \lambda_i = 1, m \in \mathbb{N} \right\}$$



# Simplices

An  $m$ -dimensional simplex is the convex hull of  $m + 1$  affinely independent vectors in  $E$ .



# Simplices and convex sets

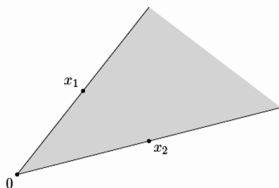
## Theorem

*The dimension of a convex set  $C$  is the largest dimension of the various simplices contained in  $C$ .*

# Definition

$K \subset E$  is a cone if it is nonempty and closed under positive scalar multiplication.

$K \subset E$  is a convex cone if it is a cone and it is convex  $\iff K$  is closed under addition and positive scalar multiplication



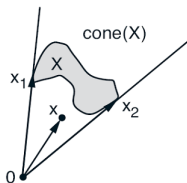
# Examples of convex cones

- (a) Nonnegative orthant  $\mathbb{R}_+^n = \{x \in \mathbb{R}^n \mid \text{each } x_i \geq 0\}$ .
- (b) Positive orthant  $\mathbb{R}_{++}^n$ .
- (c) Open and closed half-spaces determined by hyperplanes passing through the origin.
- (d) Cone of vectors with nonincreasing components  
 $\mathbb{R}_{\geq}^n = \{x \in \mathbb{R}^n \mid x_1 \geq x_2 \geq \dots \geq x_n\}$ .

# Cone generated by a set

For a set  $X \subset E$ ,

$$\begin{aligned}\text{cone}(X) &= \{\text{smallest convex cone containing } X\} \cup \{0\} \\ &= \left\{ \sum_{i=1}^m \lambda_i x_i \mid x_i \in X, \lambda_i \geq 0, m \in \mathbb{N} \right\}\end{aligned}$$





## Proposition

For a set  $S \subset E$ ,

$$\text{aff}(S) = \text{aff}(\text{conv} S)$$

## Proposition

*Let  $K$  be a convex cone containing the origin (in particular, the condition is satisfied if  $K = \text{cone}(X)$ , for some  $X$ ). Then*

$$\begin{aligned} \text{aff}(K) &= K - K \\ &= \{x - y \mid x, y \in K\} \end{aligned}$$

*is the smallest subspace containing  $K$  and  $K \cap (-K)$  is the smallest subspace contained in  $K$ .*

## Proposition

*Every convex set  $C \subset E$  can be regarded as a cross-section of a convex cone  $K \subset E \times \mathbb{R}$*

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*Every convex set  $C \subset E$  can be regarded as a cross-section of a convex cone  $K \subset E \times \mathbb{R}$*

## Proof.

Define

$$\begin{aligned} K &= \text{cone} \{(x, 1) \mid x \in C\} \\ &= \{(\lambda x, \lambda) \mid \lambda > 0, x \in C\} \cup \{0\} \end{aligned}$$

Then  $C$  can be identified with the intersection between  $K$  and the hyperplane  $\{(y, \lambda) \mid \lambda = 1\}$  □

## Theorem (Part 1)

*Let  $X$  be a nonempty subset of  $E$ . Then*

- (a) *Every nonzero  $x$  in  $\text{cone}(X)$  can be represented as a positive linear combination of vectors  $x_1, \dots, x_m$  from  $X$  that are linearly independent.*

### Sketch of proof.

*Let  $m$  be the smallest integer so that  $x$  is a positive linear combination of elements  $x_1, \dots, x_m$  from  $X$  and prove by contradiction that  $x_1, \dots, x_m$  are linearly independent.* □

## Theorem (Part 2)

Let  $X$  be a nonempty subset of  $E$ . Then

(b) Every  $x \in \text{conv}(X) \setminus X$  can be represented as a convex combination of vectors  $x_1, \dots, x_m$  from  $X$  that are affinely independent.

Therefore, a vector in  $\text{cone}(X)$  (respect.  $\text{conv}(X)$ ) may be represented by no more than  $n$  (respect.  $n + 1$ ) vectors in  $X$ .

## Sketch of proof.

Apply Part 1 to  $Y = \{(x, 1) \mid x \in X\}$ . □

## Corollary

*Let  $X$  be a nonempty compact subset of  $E$ . Then  $\text{conv}(X)$  is also a compact subset of  $E$ .*

However,  $\text{cone}(X)$  might fail to be closed even if  $X$  is compact.

If the set  $X$  is just closed,  $\text{conv}(X)$  is not necessarily closed.

