

Instructions. Answer each of the questions on your own paper. Put your name on each page of your paper. Be sure to show your work so that partial credit can be adequately assessed. *Credit will not be given for answers (even correct ones) without supporting work.* A table of Laplace transforms has been appended to the exam. The following trigonometric identities may also be of use:

$$\begin{array}{l} \sin(\theta + \varphi) = \sin \theta \cos \varphi + \sin \varphi \cos \theta \\ \cos(\theta + \varphi) = \cos \theta \cos \varphi - \sin \theta \sin \varphi \end{array}$$

1. [18 Points] Find the the general solution of the following Cauchy-Euler equations:

(a) $2t^2y'' - 3ty' + 2y = 0$.

(b) $t^2y'' + ty' + 16y = 0$.

2. [18 Points] Use *variation of parameters* to find a particular solution of the nonhomogeneous differential equation

$$t^2y'' - 4ty' + 6y = t^3.$$

You may assume that the solution of the homogeneous equation $t^2y'' - 4ty' + 6y = 0$ is $y_h = c_1t^2 + c_2t^3$.

3. [18 Points] Let f be the function defined by

$$f(t) = \begin{cases} \frac{t}{2} & \text{if } 0 \leq t < 2, \\ \frac{t}{2} - 1 & \text{if } 2 \leq t < 4, \\ 0 & \text{if } t \geq 4. \end{cases}$$

(a) Sketch the graph of $f(t)$ over the interval $[0, 6]$.

(b) Find the Laplace transform of $f(t)$.

4. [18 Points]

(a) Find the inverse Laplace transform $f(t)$ of the following function:

$$F(s) = \frac{1 + e^{-\pi s}}{s^2 + 1}$$

(b) Sketch the graph of $f(t)$.

5. [18 Points] Solve the following initial value problem:

$$y'' + y = \delta_0(t) - \delta_\pi(t) + \delta_{2\pi}(t), \quad y(0) = 0, \quad y'(0) = 0.$$

(Remember that $\delta_c(t)$ is the Dirac delta function.)

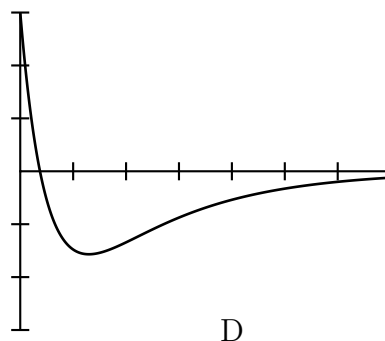
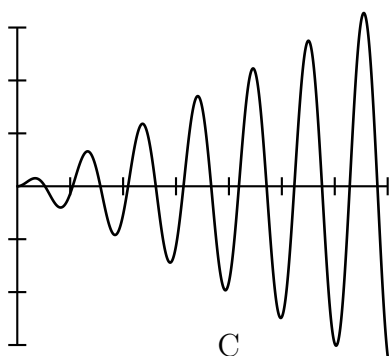
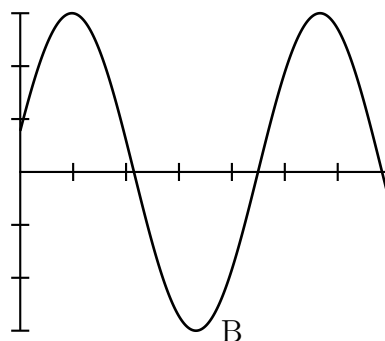
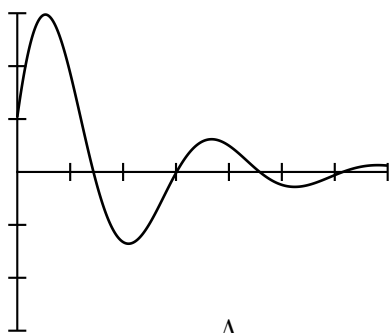
Give a careful sketch of the graph of the solution for the interval $0 \leq t \leq 3\pi$.

6. [10 Points] A mass-spring-dashpot system with forcing function $f(t)$ satisfies the differential equation

$$my'' + \mu y' + ky = f(t)$$

where m is the mass, μ the damping constant, and k is the spring constant. Each of the following differential equations represents such a system. Each of the graphs below is the graph of a solution of (exactly) one of these differential equations. Identify each graph with the equation by placing the appropriate letter in the following table. It may be useful to remember what it means for a spring system to be undamped, underdamped, or overdamped.

Equation	Graph
$9y'' + 4y = 0$	
$2y'' + 5y' + 2y = 0$	
$y'' + y' + \frac{5}{4}y = 0$	
$y'' + 9y = \cos 3t$	



Laplace Transform Table

	$f(t)$	\longleftrightarrow	$F(s) = \mathcal{L}\{f(t)\}(s)$
1.	1	\longleftrightarrow	$\frac{1}{s}$
2.	t^n	\longleftrightarrow	$\frac{n!}{s^{n+1}}$
3.	e^{at}	\longleftrightarrow	$\frac{1}{s-a}$
4.	$t^n e^{at}$	\longleftrightarrow	$\frac{n!}{(s-a)^{n+1}}$
5.	$\cos bt$	\longleftrightarrow	$\frac{s}{s^2 + b^2}$
6.	$\sin bt$	\longleftrightarrow	$\frac{b}{s^2 + b^2}$
7.	$e^{at} \cos bt$	\longleftrightarrow	$\frac{s-a}{(s-a)^2 + b^2}$
8.	$e^{at} \sin bt$	\longleftrightarrow	$\frac{b}{(s-a)^2 + b^2}$
9.	$h(t-c)$	\longleftrightarrow	$\frac{e^{-sc}}{s}$
10.	$\delta_c(t) = \delta(t-c)$	\longleftrightarrow	e^{-sc}

Laplace Transform Principles

Linearity	$\mathcal{L}\{af(t) + bg(t)\} = a\mathcal{L}\{f\} + b\mathcal{L}\{g\}$
Input Derivative Principles	$\mathcal{L}\{f'(t)\}(s) = s\mathcal{L}\{f(t)\} - f(0)$ $\mathcal{L}\{f''(t)\}(s) = s^2\mathcal{L}\{f(t)\} - sf(0) - f'(0)$
First Translation Principle	$\mathcal{L}\{e^{at}f(t)\} = F(s-a)$
Transform Derivative Principle	$\mathcal{L}\{-tf(t)\}(s) = \frac{d}{ds}F(s)$
Second Translation Principle	$\mathcal{L}\{h(t-c)f(t-c)\} = e^{-sc}F(s)$, or $\mathcal{L}\{g(t)h(t-c)\} = e^{-sc}\mathcal{L}\{g(t+c)\}$.
The Convolution Principle	$\mathcal{L}\{(f * g)(t)\}(s) = F(s)G(s)$.

Partial Fraction Expansion Theorems

The following two theorems are the main partial fractions expansion theorems, as presented in the text.

Theorem 1 (Linear Case). *Suppose a proper rational function can be written in the form*

$$\frac{p_0(s)}{(s - \lambda)^n q(s)}$$

and $q(\lambda) \neq 0$. Then there is a unique number A_1 and a unique polynomial $p_1(s)$ such that

$$\frac{p_0(s)}{(s - \lambda)^n q(s)} = \frac{A_1}{(s - \lambda)^n} + \frac{p_1(s)}{(s - \lambda)^{n-1} q(s)}. \quad (1)$$

The number A_1 and the polynomial $p_1(s)$ are given by

$$A_1 = \frac{p_0(\lambda)}{q(\lambda)} \quad \text{and} \quad p_1(s) = \frac{p_0(s) - A_1 q(s)}{s - \lambda}. \quad (2)$$

Theorem 2 (Irreducible Quadratic Case). *Suppose a real proper rational function can be written in the form*

$$\frac{p_0(s)}{(s^2 + cs + d)^n q(s)},$$

where $s^2 + cs + d$ is an irreducible quadratic that is factored completely out of $q(s)$. Then there is a unique linear term $B_1s + C_1$ and a unique polynomial $p_1(s)$ such that

$$\frac{p_0(s)}{(s^2 + cs + d)^n q(s)} = \frac{B_1s + C_1}{(s^2 + cs + d)^n} + \frac{p_1(s)}{(s^2 + cs + d)^{n-1} q(s)}. \quad (3)$$

If $a + ib$ is a complex root of $s^2 + cs + d$ then $B_1s + C_1$ and the polynomial $p_1(s)$ are given by

$$B_1(a + ib) + C_1 = \frac{p_0(a + ib)}{q(a + ib)} \quad \text{and} \quad p_1(s) = \frac{p_0(s) - (B_1s + C_1)q(s)}{s^2 + cs + d}. \quad (4)$$