Topological and geodesic complexity of *n*-dimensional Klein bottle

Don Davis

Gainesville Special Session, November, 2019

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$$\overline{M}(\ell) = \overline{M}(\ell_1, \dots, \ell_n) = \{(z_1, \dots, z_n) \in (S^1)^n : \sum \ell_i z_i = 0\} / O(n)$$



(n-3)-manifold if generic (no straight-line polygons)

134 7-gon spaces, 2469 8-gon spaces

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For most ℓ , $2n-7 \leq \mathrm{TC}(\overline{M}(\ell)) \leq 2n-6$.

e.g., of the 2469 8-gon spaces, 2465 satisfy this, two do not, and for two, it is not known.

$$\overline{M}(\frac{1}{n}, \dots, \frac{1}{n}, 1, 1, 1) \approx T^{n-3}$$
. TC = $n - 3$.

 $\overline{M}(1,\ldots,1,n-2) \approx RP^{n-3}$. TC = imm dim, usually < 2n-7.

These are the only known examples of $TC(\overline{M}(\ell)) < 2n - 7$.

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$$\overline{M}(\frac{1}{n}, \dots, \frac{1}{n}, 1, 1, 1, 2).$$
$$H^*(-) \Rightarrow \mathrm{TC} \ge n - 1 \text{ for } n \ge 6.$$

$$\approx K_n = \mathbf{R}^n / (x + e_i \sim x), \ i < n, (x_1, \dots, x_n) \sim (1 - x_1, \dots, 1 - x_{n-1}, x_n + 1)$$

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$GC(X) = \min\{k : \exists E_0 \sqcup \cdots \sqcup E_k = X \times X \text{ with continuous choice of geodesics on } E_i\}.$

Theorem (with David Recio-Mitter). $GC(K_n) = 2n$.

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For $P \in I^n$, $\mathcal{R}(P) = \text{polytope centered at } P$ bounded by \bot bisectors of segments from P to equivalent points. Interior is points with unique geodesic from P.



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Let $\mathcal{D}_{\alpha} = D_1 \times \cdots \times D_n$, with

$$D_i = \begin{cases} ((0, \frac{1}{2}) \cup (\frac{1}{2}, 1))^{n-1} \text{ or } \{0, \frac{1}{2}\} & i < n \\ (0, 1) \text{ or } \{0\} & i = n. \end{cases}$$

On \mathcal{D}_{α} , $\mathcal{R}(P)$ varies continuously bijectively with P, preserving \sim .

Let $R_j(P)$ be the set of equivalence classes of *j*-faces of $\mathcal{R}(P)$. Choose a representative of each equivalence class, and let $R'_j(P)$ denote their union.

Let
$$E_{\alpha,j} = \{(p(P), p(Q)) : P \in \mathcal{D}_{\alpha}, Q \in R'_j(P)\}.$$

Geodesic motion planning rule on $E_{\alpha,j}$: $s(p(P), p(Q)) = p(\sigma_{P,Q})$, where $\sigma_{P,Q}$ is linear path from P to Q.

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Geodesic motion planning rule on $E_{\alpha,j}$: $s(p(P), p(Q)) = p(\sigma_{P,Q})$, where $\sigma_{P,Q}$ is linear path from P to Q. **Proposition**. If dim $(\mathcal{D}_{\alpha}) + j = \dim(\mathcal{D}_{\alpha'}) + j'$, then $E_{\alpha,j}$ and $E_{\alpha',j'}$ are topologically disjoint.

Corollary. $GC(K_n) \leq 2n$.

Proof. Have geodesic MP rules on S_0, \ldots, S_{2n} , where

$$S_i = \bigcup_{\dim(\mathcal{D}_\alpha) + j = i} E_{\alpha,j}.$$

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If n = 6, the domain $(0, \frac{1}{2})^5 \times (0, 1)$, must be split into parts separated by $\sum_{i=1}^{5} (a_i - \frac{1}{4})^2 = \frac{1}{16}$. When it is $< \frac{1}{16}$, the top and bottom pyramids

intersect inside the walls, and the top and bottom pyramids need to be truncated above and below. So there is not a uniform way to choose geodesics in polytopes of the two types.