## Reconstruction and Higher Dimensional Geometry

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#### Abstract

Tutte proved that, if two graphs, both with more than two vertices, have the same collection of vertex-deleted subgraphs, then the determinants of the two corresponding adjacency matrices are the same. In this paper, we give a geometric proof of Tutte's theorem using vectors and angles. We further study the lowest eigenspaces of these adjacency matrices.

#### 1 Introduction

Given the graph  $G = \{V, E\}$ , let  $G_i$  be the graph obtained by deleting the i-th vertex  $v_i$ . Fix  $n \geq 3$  from now on. Let G and H be two graphs of n vertices. The main conjecture in reconstruction theory, states that if  $G_i$  is isomorphic to  $H_i$  for every i, then G and H are isomorphic (up to a reordering of V). This conjecture is also known as the Ulam's conjecture.

The reconstruction conjecture can be formulated in purely algebraic terms. Consider two  $n \times n$  real symmetric matrices A and B. Let  $A_i$  and  $B_i$  be the matrices obtaining by deleting the i-th row and i-th column of A and B, respectively.

**Definition 1** Let  $\sigma_i$  be a n-1 by n-1 permutation matrix. Let A and B be two  $n \times n$  real symmetric matrices. We say that A and B are hypomorphic if there exists a set of  $n-1 \times n-1$  permutation matrices

$$\{\sigma_1, \sigma_2, \ldots, \sigma_n\},\$$

such that  $B_i = \sigma_i A_i \sigma_i^t$  for every i. Put  $\Sigma = {\sigma_1, \sigma_2, \ldots, \sigma_n}$ . We write  $B = \Sigma(A)$ .  $\Sigma$  is called a hypomorphism.

The algebraic version of the reconstruction conjecture can be stated as follows.

**Conjecture 1** Let A and B be two  $n \times n$  symmetric matrices. If there exists a hypomorphism  $\Sigma$  such that  $B = \Sigma(A)$ , then there exists a  $n \times n$  permutation matrix  $\tau$  such that  $B = \tau A \tau^t$ .

We start by fixing some notations. If M is a symmetric real matrix, then the eigenvalues of M are real. We write

$$eigen(M) = (\lambda_1(M) \ge \lambda_2(M) \ge \dots \ge \lambda_n(M)).$$

If  $\alpha$  is an eigenvalue of M, we denote the corresponding eigenspace by  $eigen_{\alpha}(M)$ . Let  $\mathbf{1}_n$  be the n-dimensional row vector  $(1,1,\ldots,1)$ . We may drop the subscript n if it is implicit. Put  $J=\mathbf{1}^t\mathbf{1}$ . If A and B are hypomorphic, so are A+tJ and B+tJ.

**Theorem 1 (Tutte)** Let B and A be two real  $n \times n$  symmetric matrices. If B and A are hypomorphic then  $\det(B - \lambda I + tJ) = \det(A - \lambda I + tJ)$  for all  $t, \lambda \in \mathbb{R}$ .

In this paper, we will study the geometry related to Conjecture 1. Out main result can be stated as follows.

**Theorem 2 (Main Theorem)** Let B and A be two real  $n \times n$  symmetric matrices. Let  $\Sigma$  be a hypomorphism such that  $B = \Sigma(A)$ . Let t be a real number. Then there exists an open interval T such that for  $t \in T$  we have

- 1.  $\lambda_n(A+tJ) = \lambda_n(B+tJ);$
- 2.  $eigen_{\lambda_n}(A+tJ)$  and  $eigen_{\lambda_n}(B+tJ)$  are both one dimensional;
- 3.  $eigen_{\lambda_n}(A+tJ) = eigen_{\lambda_n}(B+tJ)$ .

A similar statement holds for the highest eigenspaces.

Since the sets of majors of A+tJ and of B+tJ are the same, for every  $t\in T$  and  $\lambda\in\mathbb{R}$ ,

$$\det(A + tJ - \lambda I) - \det(B + tJ - \lambda I) = \det(A + tJ) - \det(B + tJ). \tag{1}$$

If  $t \in T$ , by taking  $\lambda = \lambda_n(A + tJ)$ , we obtain

$$\det(A+tJ) - \det(B+tJ) = \det(A+tJ-\lambda I) - \det(B+tJ-\lambda I) = 0.$$

Since the above statement is true for  $t \in T$ ,  $\det(A+tJ) = \det(B+tJ)$  for every t. By Equation. 1, we obtain  $\det(B-\lambda I+tJ) = \det(A-\lambda I+tJ)$  for all  $t,\lambda \in \mathbb{R}$ . This is Tutte's theorem, which was proved using rank polynomials and Hamiltonian circuits. I should also mention that Kocay [1] found a simpler way to deduce the reconstructibility of characteristic polynomials.

Here is the content of this paper. We begin by presenting a positive semidefinite matrix  $A + \lambda I$  by n vectors in  $\mathbb{R}^n$ . We then interpret the reconstruction conjecture as a generalization of a congruence theorem in Eulidean geometry. Next we study the presentations of  $A + \lambda I$  under the perturbation by tJ. We define a norm of angles in higher dimensions and establish a comparison theorem. Our comparison theorem then forces hypomorphic matrices to have the same lowest eigenvalue and eigenvector.

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#### 2 Notations

Unless stated otherwise,

- 1. all linear spaces in this paper will be finite dimensional real Euclidean spaces;
- 2. all linear subspaces will be equipped with the induced Euclidean metric;
- 3. all vectors will be column vectors;
- 4. vectors are sometimes regarded as points in  $\mathbb{R}^n$ .

Let  $U = \{u_1, u_2, \dots u_m\}$  be an ordered set of m vectors in  $\mathbb{R}^n$ . U is also interpreted as a  $n \times m$  matrix.

1. Let conv U be the convex hull spanned by U, namely,

$$\{\sum_{i=1}^{m} \alpha_i u_i \mid \alpha_i \ge 0, \sum_{i=1}^{m} \alpha_i = 1\}.$$

2. Let aff U be the affine space spanned by U, namely,

$$\{\sum_{i=1}^{m} \alpha_i u_i \mid \sum_{i=1}^{m} \alpha_i = 1\}.$$

3. Let span U be the linear span of U, namely,

$$\{\sum_{i=1}^{m} \alpha_i u_i \mid \alpha_i \in \mathbb{R}\}.$$

Then conv  $U \subset \text{aff } U \subset \text{span } U$ .

Let A be a matrix. We denote the (i, j)-th entry of A by  $a_{ij}$ . We denote the transpose of A by  $A^t$ . Let  $\mathbb{R}^{+n}$  be the set of vectors with only positive coordinates.

## 3 Geometric Interpretation

Fix a standard Euclidean space  $(\mathbb{R}^n, (,))$ .

**Definition 2** Let A be a symmetric positive semidefinite real matrix. An ordered set of vectors  $V = \{v_1, v_2, \dots v_n\}$  is said to be a presentation of A if and only if  $(v_i, v_j) = a_{ij}$ .

Regarding  $v_i$  as column vectors and V as a  $n \times n$  matrix, V is a presentation of A if and only if  $V^tV = A$ . Every positive semidefinite real matrix A has a presentation. In addition, the presentation V is unique up to a left multiplication by an orthogonal matrix.

**Definition 3** Let S and T be two sets of vectors in  $\mathbb{R}^n$ . S and T are said to be congruent if there exists an orthogonal linear transformation in  $\mathbb{R}^n$  that maps S onto T.

So  $A = \sigma B \sigma^t$  for some permutation  $\sigma$  if and only if A and B are presented by two congruent subsets in  $\mathbb{R}^n$ .

Now consider two hypomorphic matrices  $B = \Sigma(A)$ . Observe that  $B + \lambda I = \Sigma(A + \lambda I)$ . Without loss of generality, assume A and B are both positive semidefinite. Let U and V be their presentations respectively. Since  $B_i = \sigma_i A_i \sigma_i^t$ ,  $U - \{u_i\}$  is congruent to  $V - \{v_i\}$ . Then the reconstruction conjecture can be stated as follows.

Conjecture 2 (Geometric reconstruction) Let

$$S = \{u_1, u_2, \dots, u_n\}$$

and

$$T = \{v_1, v_2, \dots v_n\}$$

be two finite sets of vectors in  $\mathbb{R}^m$ . Assume that  $S - \{u_i\}$  is congruent to  $T - \{v_i\}$  for every i. Then S and T are congruent.

Generically, m = n.

**Definition 4** We say that  $U = \{u_i\}_{1}^{n}$  is in good position if the point 0 is in the interior of the convex hull of U and the convex hull of U is of dimension n-1.

**Lemma 1** Let A be a symmetric positive semidefinite matrix. The following are equivalent.

1. A has a presentation in good position.

- 2. Every presentation of A is in good position.
- 3. rank(A) = n 1 and  $eigen_0(A) = \mathbb{R}\alpha$  for some  $\alpha \in (\mathbb{R}^+)^n$ .

Proof: Since A is symmetric positive semidefinite, A has a presentation. Let U be a presentation of A.

If U is in good position, then every presentation obtained from an orthogonal linear transformation is also in good position. Since a presentation is unique up to an orthogonal linear transformation,  $(1) \leftrightarrow (2)$ .

Suppose U is in good position. Then rank(U) = n - 1. So rank(A) = n - 1. Since 0 is in the interior of the convex hull of U, there exists  $\alpha = (\alpha_1, \alpha_2, \dots \alpha_n)^t$  such that

$$0 = \sum_{1}^{n} \alpha_i u_i; \qquad \sum_{1}^{n} \alpha_i = 1; \qquad \alpha_i > 0 \ \forall \ i.$$

Since rank(U) = n - 1,  $\alpha$  is unique. Now  $U\alpha = 0$  implies

$$A\alpha = U^t U \alpha = U^t 0 = 0.$$

Since rank(A) = rank(U) = n - 1,  $eigen_0(A) = \mathbb{R}\alpha$ . So (2)  $\rightarrow$  (3).

Conversely, suppose rank(A) = n-1 and  $eigen_0(A) = \mathbb{R}\alpha$  with  $\alpha \in \mathbb{R}^{+n}$ . Then  $\sum_i \alpha_i u_i = 0$  and the linear span U is of dimension n-1. Thus, 0 is in conv U. It follows that aff  $U = \operatorname{span} U$ . So  $\dim(\operatorname{conv} U) = \dim(\operatorname{aff} U) = \dim(\operatorname{span} U) = n-1$ . So  $(3) \to (1)$ . Q.E.D.

**Lemma 2** Let U be a presentation of A. Suppose that U is in good position. Let  $\alpha_i$  be the volume of the convex hull of  $\{0, u_1, u_2, \dots, \hat{u_i}, \dots, u_n\}$ . Then

$$\alpha = (\alpha_1, \alpha_2, \dots, \alpha_n)^t$$

is a lowest eigenvector.

The proof can be found in many places. For the sake of completeness, I will give a proof using the language of exterior product.

Proof: Choosing an orthonormal basis properly, we may assume that every  $u_i \in \mathbb{R}^{n-1}$ . U becomes a  $(n-1) \times n$  matrix. Let  $x_1, x_2 \dots x_{n-1}$  be the row vectors of U. Consider the exterior product

$$x_1 \wedge x_2 \wedge \ldots \wedge x_{n-1}$$
.

Let  $\beta_i$  be the *i*-th coordinate in terms of the standard basis

$$\{(-1)^{i-1}e_1 \wedge e_2 \wedge \ldots \wedge \hat{e_i} \wedge \ldots \wedge e_n \mid i \in [1, n]\}.$$

Put  $\beta = (\beta_1, \beta_2, \dots, \beta_n)^t$ . Notice that  $x_i \wedge (x_1 \wedge x_2 \wedge \dots \wedge x_{n-1}) = 0$  for  $1 \leq i \leq n-1$ . Therefore,  $(x_i, \beta) = 0$  for every i. So  $U\beta = 0$ . It follows that  $\sum_{i=1}^n \beta_i u_i = 0$ . Since 0 is in the convex hull of  $\{u_i\}_1^n$ ,  $\beta_i$  must be either all negative or all positive. Clearly,

$$|\beta_i| = |u_1 \wedge \ldots \wedge \hat{u_i} \wedge \ldots \wedge u_n| = (n-1)!\alpha_i.$$

Therefore, we have  $U\alpha = 0$ . Then  $A\alpha = U^tU\alpha = 0$ .  $\alpha$  is a lowest eigenvector. Q.E.D.

**Theorem 3** Suppose that  $B = \Sigma(A)$ . Suppose that A and B have presentations in good position. Then  $eigen_0(A) = eigen_0(B) \cong \mathbb{R}$ .

Proof: Let U and V be presentations of A and B respectively. Then U and V are in good position. Notice that the volume of the convex hull of

$$\{0, u_1, u_2, \dots, \hat{u_i}, \dots u_n\}$$

equals the volume of the convex hull of

$$\{0, v_1, v_2, \dots, \hat{v_i}, \dots v_n\}$$

By Lemma 2 and Lemma 1,  $eigen_0(A) = eigen_0(B) \cong \mathbb{R}$ . So the lowest eigenspace of A is equal to the lowest eigenspace of B. Q.E.D.

### 4 Perturbation by J

Recall that  $J = \mathbf{1}_n^t \mathbf{1}_n$ . We know that  $B = \Sigma(A)$  if and only if  $B + tJ = \Sigma(A + tJ)$ . Let us see how presentations of A + tJ depend on t. Let A be a positive definite matrix. Let  $U = \{u_i\}_1^n$  be a presentation of A.

Let aff U be the affine space spanned by U. Then  $\{u_i\}$  are affinely independent. Let  $u_0$  be the orthogonal projection of the origin onto aff U. Then  $(u_0, u_i - u_0) = 0$  for every i. We obtain

$$U^t u_0 = ||u_0||^2 \mathbf{1}.$$

It follows that  $u_0 = ||u_0||^2 (U^t)^{-1} \mathbf{1}$ . Consequently,

$$||u_0||^2 = (u_0, u_0) = ||u_0||^4 \mathbf{1}^t U^{-1} (U^t)^{-1} \mathbf{1} = ||u_0||^4 \mathbf{1}^t A^{-1} \mathbf{1}.$$

Clearly,  $||u_0||^2 = \frac{1}{1^t A^{-1} 1}$ . We obtain the following lemma.

**Lemma 3** Let A be a positive definite matrix. Let  $U = \{u_i\}_1^n$  be a presentation of A. Let  $u_0$  be the orthogonal projection of the origin onto aff U. Then  $||u_0||^2 = \frac{1}{1^t A^{-1} 1}$  and

$$u_0 = \frac{1}{\mathbf{1}^t A^{-1} \mathbf{1}} (U^t)^{-1} \mathbf{1}.$$

Consider  $\{u_i - su_0\}_{1}^{n}$ . Notice that

$$(u_i - su_0, u_j - su_0) = (u_i - u_0 + (1 - s)u_0, u_j - u_0 + (1 - s)u_0) = (u_i - u_0, u_j - u_0) + (1 - s)^2(u_0, u_0).$$

Taking s = 0, we have

$$(u_i, u_j) = (u_i - u_0, u_j - u_0) + (u_0, u_0).$$

Therefore

$$(u_i - su_0, u_i - su_0) = (u_i, u_i) - (u_0, u_0) + (1 - s)^2 (u_0, u_0) = (u_i, u_i) + (s^2 - 2s) ||u_0||^2$$

We see clearly that  $A + (s^2 - 2s) \|u_0\|^2 J$  is presented by  $\{u_i - su_0\}_1^n$ . Observe that

$$span(u_1 - su_0, u_2 - su_0, \dots, u_n - su_0)$$

is of dimension n for all  $s \neq 1$ . So  $A + (s^2 - 2s) \|u_0\|^2 J$  is positive definite for all  $s \neq 1$ . If s = 1, we see that  $A - \|u_0\|^2 J$  is presented by  $\{u_i - u_0\}_1^n$  whose linear span is of dimension n - 1. We obtain the following lemma.

**Lemma 4** Let A be a symmetric positive definite matrix. Let U be a presentation of A. Let  $u_0$  be the orthogonal projection of the origin onto aff U. Then  $\{u_i - su_0\}_1^n$  is a presentation of  $A + (s^2 - 2s)||u_0||^2 J$ . Let  $t = (s^2 - 2s)||u_0||^2$ . Then A + tJ is positive definite for all  $t > -||u_0||^2$  and positive semidefinite for  $t = -||u_0||^2$ .

Notice that

$$u_0 = \frac{1}{\mathbf{1}^t A^{-1} \mathbf{1}} (U^t)^{-1} \mathbf{1} = \frac{1}{\mathbf{1}^t A^{-1} \mathbf{1}} U(U^{-1} (U^t)^{-1}) \mathbf{1} = \frac{1}{\mathbf{1}^t A^{-1} \mathbf{1}} UA^{-1} \mathbf{1}.$$

**Theorem 4** Let A be a symmetric positive definite matrix. Let U be a presentation of A. Let  $u_0$  be the orthogonal projection of the origin onto aff U. Then  $u_0 = \frac{1}{\mathbf{1}^t A^{-1} \mathbf{1}} U A^{-1} \mathbf{1}$  and the following are equivalent.

- 1.  $A ||u_0||^2 J$  has a presentation in good position;
- 2.  $u_0$  is in the interior of conv U;
- 3.  $A^{-1}\mathbf{1} \in \mathbb{R}^{+^n}$

**Corollary 1** Let A be a real symmetric matrix. There exists  $\lambda_0$  such that for every  $\lambda \geq \lambda_0$  there exists a real number t such that  $A + \lambda I + tJ$  has a presentation in good position.

Proof: Instead, consider I + sA with  $s = \frac{1}{\lambda}$ . I + sA is related to  $A + \lambda I$  by a constant multiplication:

$$\lambda(I + sA) = \lambda I + A.$$

Let  $s_0 = \frac{1}{\|A\|+1}$  where  $\|A\|$  denote the operator norm. Suppose that  $0 \le s \le s_0$ . Then I + sA is positive definite. For s = 0,  $(I + sA)^{-1}\mathbf{1} \in \mathbb{R}^{+n}$ . Since

$$s \to (I + sA)^{-1} \mathbf{1}$$

is continuous on  $(0, s_0)$ , there exists a  $s_1 \in (0, s_0)$  such that  $(I + sA)^{-1}\mathbf{1} \in \mathbb{R}^{+n}$  for every  $s \in (0, s_1]$ . So for every  $\lambda \in [\frac{1}{s_1}, \infty)$ ,  $(A + \lambda I)^{-1}\mathbf{1} = \lambda^{-1}(sA + I)^{-1}\mathbf{1} \in \mathbb{R}^{+n}$ . Let  $\lambda_0 = \frac{1}{s_1}$ . So for every  $\lambda \geq \lambda_0$ ,  $(A + \lambda I)^{-1}\mathbf{1} \in \mathbb{R}^{+n}$ . By Theorem 4, for every  $\lambda \geq \lambda_0$  there exists a t such that  $A + \lambda I + tJ$  has a presentation in good position. Q.E.D.

# 5 Higher Dimensional Angle and Comparison Theorem

**Definition 5** Let  $U = \{u_1, u_2, \dots u_n\}$  be a subset in  $\mathbb{R}^n$ .  $\mathbb{R}^n$  may be contained in some other Euclidean space. Let u be a point in  $\mathbb{R}^n$ . The angle  $\angle(u, U)$  is defined to be the region

$$\{\sum_{1}^{n} \alpha_i(u_i - u) \mid \alpha_i \ge 0\}.$$

Two angles are congruent if there exists an isometry that maps one angle to the other. Let  $\mathcal{B}$  be the unit ball in  $\mathbb{R}^n$ . The norm of  $\angle(u,U)$  is defined to be the volume of  $\angle(u,U) \cap \mathcal{B}$ , denote it by  $|\angle(u,U)|$ .

Let me make a few remarks.

- 1. Firstly, if two angles are congruent, their norms are the same. But, unlike the 2 dimensional case, if the norms of two angles are the same, these two angles may not be congruent.
- 2. Secondly, if  $\{u_i u\}_1^n$  are linearly dependent, then  $|\angle(u, U)| = 0$ . If u happens to be in aff U, then  $|\angle(u, U)| = 0$ .

- 3. According to our definition,  $|\angle(u,U)|$  is always less than half of the volume of  $\mathcal{B}$ .
- 4. More generally, one can allow  $\{\alpha_i\}_1^n$  to be in a collection of other sign patterns which correspond to quadrants in two dimensional case. Then the norm of an angle can be greater than half of the volume of  $\mathcal{B}$ .

**Lemma 5** If  $\angle(u,U) \subseteq \angle(u,V)$ , then  $|\angle(u,U)| \le |\angle(u,V)|$ . If  $|\angle(u,U)| > 0$  and  $\angle(u,U)$  is a proper subset of  $\angle(u,V)$  then  $|\angle(u,U)| < |\angle(u,V)|$ .

**Theorem 5 (Comparison Theorem)** Let  $\angle(u,U)$  be an angle and  $|\angle(u,U)| \neq 0$ . Suppose that v is contained in the interior of the convex hull of  $\{u\} \cup U$ . Then  $|\angle(u,U)| < |\angle(v,U)|$ .

Proof: Without loss of generality, assume u=0. Suppose  $|\angle(0,U)|>0$ . Let  $U=\{u_1,u_2,\ldots u_n\}$ . Then U is linearly independent. Since v is in the interior of  $\operatorname{conv}(0,U)$ , v can be written as

$$\sum_{i=1}^{n} \alpha_i u_i$$

with  $\alpha_i \in \mathbb{R}^+$  and  $\sum_i^n \alpha_i < 1$ .

Let  $U' = \{u_i - v\}_1^n$ . It suffices to prove that  $\angle(0, U)$  is a proper subset of  $\angle(0, U')$ . Let x be a point in  $\angle(0, U)$  with  $x \neq 0$ . Then  $x = \sum_i x_i u_i$  for some  $x_i \geq 0$  with  $\sum_i x_i > 0$ . Define for each i

$$y_i = x_i + \alpha_i \frac{\sum x_i}{1 - \sum \alpha_i}$$

The reader can easily verify that  $\sum y_i(u_i - v) = x$ . Observe that  $y_i > x_i \ge 0$ . So  $\angle(0, U)$  is a proper subset of  $\angle(0, U')$ . It follows that

$$|\angle(0, U)| < |\angle(0, U')| = |\angle(v, U)|.$$

Q.E.D.

**Theorem 6** Let  $U = \{u_1, u_2, \dots, u_n\} \subset \mathbb{R}^m$  for some  $m \geq n$ . Suppose that  $|\angle(u, U)| > 0$ . Suppose that the orthogonal projection of u onto aff U is in the interior of conv U. Let v be a vector such that  $(u - v, u - u_i) = 0$  for every i. If  $u \neq v$  then  $|\angle(u, U)| > |\angle(v, U)|$ .

Proof: Without loss of generality, assume that u = 0. Then U is linearly independent and  $v \perp u_i$  for every i. Let  $u_0$  be the orthogonal projection of u onto aff U. By our assumption,  $u_0$  is in the interior of conv U and  $||u_0|| \neq 0$ . Let

$$v' = (1 - \sqrt{\frac{\|v\|^2}{\|u_0\|^2} + 1})u_0.$$

Then

$$\|v' - u_0\|^2 = (\frac{\|v\|^2}{\|u_0\|^2} + 1)\|u_0\|^2 = \|v\|^2 + \|u_0\|^2.$$

Notice that  $v \perp u_i$  and  $u_0 \perp u_i - u_0$ . We obtain

$$(u_{i} - v', u_{j} - v') = (u_{i} - u_{0} + \sqrt{\frac{\|v\|^{2}}{\|u_{0}\|^{2}} + 1} u_{0}, u_{j} - u_{0} + \sqrt{\frac{\|v\|^{2}}{\|u_{0}\|^{2}} + 1} u_{0})$$

$$= (u_{i} - u_{0}, u_{j} - u_{0}) + (\frac{\|v\|^{2}}{\|u_{0}\|^{2}} + 1) \|u_{0}\|^{2}$$

$$= (u_{i} - u_{0}, u_{j} - u_{0}) + (u_{0}, u_{0}) + (v, v)$$

$$= (u_{i}, u_{j}) + (v, v)$$

$$= (u_{i} - v, u_{j} - v).$$

$$(2)$$

Hence  $\angle(v,U) \cong \angle(v',U)$ . Notice that  $1-\sqrt{\frac{\|v\|^2}{\|u_0\|^2}+1} < 0$ . So the origin sits between v' and  $u_0$  which is in the interior of conv U. Therefore, 0 is in the interior of  $\angle(v',U)$ . By the Comparison Theorem,  $|\angle(v',U)| > |\angle(0,U)|$ . Consequently,  $|\angle(v,U)| > |\angle(0,U)|$ . Q.E.D.

**Theorem 7** Suppose that  $B = \Sigma(A)$ . Let  $\lambda_0$  be as in Cor. 1 for both B and A. Fix  $\lambda \geq \lambda_0$ . Let  $t_1$  and  $t_2$  be two real numbers such that  $A + \lambda I + t_1 J$  and  $B + \lambda I + t_2 J$  have presentations in good position. Then  $t_1 = t_2$ .

Proof: We prove by contradiction. Without loss of generality, suppose that  $t_1 > t_2$ . Let U be a presentation of  $A + \lambda I + t_1 J$ . Then U is in good position. So 0 is in the interior of conv U. Let V be a representation of  $B + \lambda I + t_2 J$ . Then V is in good position. So 0 is in the interior of conv V and dim(span V) = n - 1. Let  $v_0 \perp$  span V and  $||v_0||^2 = t_1 - t_2$ . Let  $V' = \{v_i + v_0\}_1^n$ . Clearly, V' is a presentation of  $B + \lambda I + t_1 J$ .

By Thm. 6, for every i,

$$|\angle(0, V \setminus \{v_i\})| > |\angle(-v_0, V \setminus \{v_i\})| = |\angle(0, V' \setminus \{v_i + v_0\})|.$$

Since  $B + \lambda I + t_1 J = \Sigma(A + \lambda I + t_1 J)$ ,  $V' \setminus \{v_i + v_0\}$  is congruent to  $U \setminus \{u_i\}$  for every i. Therefore  $|\angle(0, V' \setminus \{v_i + v_0\})| = |\angle(0, U \setminus \{u_i\})|$ . Since 0 is in the interiors of the convex hulls of U and of V, we have

$$Vol(\mathcal{B}) = \sum_{i=1}^{n} |\angle(0, V \setminus \{v_i\})| > \sum_{i=1}^{n} |\angle(0, V' \setminus \{v_i + v_0\})| = \sum_{i=1}^{n} |\angle(0, U \setminus \{u_i\})| = Vol(\mathcal{B}).$$

This is a contradiction. Therefore,  $t_1 = t_2$ . Q.E.D.

### 6 Proof of the Main Theorem

Suppose  $B = \Sigma(A)$ . Suppose  $\lambda_0$  satisfies Cor. 1 for both A and B. So for every  $\lambda \geq \lambda_0$  there exist real numbers  $t_1$  and  $t_2$  such that  $A + \lambda I + t_1 J$  has a presentation in good position and  $B + \lambda I + t_2 J$  has a presentation in good position. By Theorem 7,  $t_1 = t_2$ . Because of the dependence on  $\lambda$ , put  $t(\lambda) = t_1 = t_2$ . By Theorem 3,

$$eigen_0(A + \lambda I + t(\lambda)J) = eigen_0(B + \lambda I + t(\lambda)J) \cong \mathbb{R}.$$

Since 0 is the lowest eigenvalue of  $A + \lambda I + t(\lambda)J$  and  $B + \lambda I + t(\lambda)J$ ,  $\lambda$  is the lowest eigenvalue of  $A + t(\lambda)J$  and  $B + t(\lambda)J$ . In addition,

$$eigen_{-\lambda}(A + t(\lambda)J) = eigen_{-\lambda}(B + t(\lambda)J) \cong \mathbb{R}.$$

Now it suffices to show that  $t([\lambda_0, \infty))$  covers a nonempty open interval.

By Lemme 4 and Lemma 3,

$$t(\lambda) = -\|u_0\|^2 = -\frac{1}{\mathbf{1}^t (A + \lambda I)^{-1} \mathbf{1}}.$$

So  $t(\lambda)$  is a rational function. Clearly,  $t([\lambda_0, \infty))$  contains a nonempty open interval T. For  $t \in T$ , we have  $\lambda_n(A+tJ) = \lambda_n(B+tJ)$  and  $eigen_{\lambda_n}(A+tJ) = eigen_{\lambda_n}(B+tJ) \cong \mathbb{R}$ . This finishes the proof of Theorem 1. Q.E.D.

Tutte's proof involves certain polynomials associated with a graph. It is algebraic in nature. The main instrument in our proof is the comparison theorem. Presumably, there is a connection between the geometry in this paper and the polynomials defined in Tutte's paper. In particular, given n unit vectors  $u_1, u_2, \ldots u_n$ , can we compute the function  $|\angle(0, U)|$  explicitly in terms of  $U^tU = A$ ? This question turns out to be hard to answer. The norm  $|\angle(0, U)|$  as a function of A may be closely related to the functions studied in Tutte's paper [2].

### References

- [1] [K] W. L. Kocay, "An extension of Kelly's Lemma to Spanning Graphs", Congr. Numer. (31), 1981, (109-120).
- [2] [Tutte] W. T. Tutte, "All the King's Horses (A Guide to Reconstruction)", Graph Theory and Related Topics, Academic Press, 1979, (15-33).