Stabilization of a Chain of Exponential Integrators Using a Strict Lyapunov Function

Michael Malisoff

Miroslav Krstic

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Theorem: The closed loop system is GAS to (X_r, Y^*) on $(0, \infty)^2$.



Fig. 1: X (Left), Y (Right), D = 5Y/X (Bottom). $Y^* = X_r = 1$. $D^* = 5$.



Fig. 2: (X(t), Y(t)) Converging to (1, 1) through Level Curves of V.

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Theorem: We can build a function $\mathcal{R}:[0,\infty)\to [1,\infty)$ such that

$$V_{3}(x, y) = \int_{0}^{V_{1}(x, y)} \mathcal{R}(s) ds - xy, \text{ where}$$

$$V_{1}(x, y) = x + e^{-x} - 1 + \frac{Y^{*}}{D^{*}}(e^{y} - y - 1)$$

satisfies $V_3(x,y) \geq rac{1}{2}V_1(x,y)$ for all $(x,y) \in \mathbb{R}^2$ and

$$\dot{V}_3(x,y) \leq -rac{1}{2} \left\{ \mathcal{R}(V_1(x,y)) e^{-x} Y^* (1-e^y)^2 + D^* x (1-e^{-x})
ight\}$$

along all solutions (x(t), y(t)) so V_3 is a strict Lyapunov function.

Other changes of coordinates cover

$$\left\{ \begin{array}{rcl} \dot{X} &=& G(t,X,Y)X\\ \dot{Y} &=& H(t,X,Y,D)Y, \ (X,Y)\in (0,\infty)^2 \end{array} \right.$$

for many choices of G and H.

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Predator-prey model for lynxes and hares:

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Thank you for your attention!