Stability Analysis of Switched Systems with Time-Varying Discontinuous Delays

> Frederic Mazenc Michael Malisoff Hitay Ozbay

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- ▷ Briat, Fridman, Liberzon, Liu-Teel, Mancilla-Aguilar-Garcia,...

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(\Sigma)

on \mathbb{R}^n , with $\tau : [0, +\infty) \to [0, \tau_b]$ piecewise continuous and the switching times t_i for the switching signal $\sigma : [0, +\infty) \to \{1, ..., k\}$ admitting constants \mathcal{T}_i such that $0 < \mathcal{T}_1 < t_{i+1} - t_i \leq \mathcal{T}_2$ for all *i*.

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We place certain growth or decay conditions on suitable functions V_i along solutions of the *i*th subsystem

$$\dot{\mathbf{x}}(t) = f_{\sigma(t_i)}(t, \mathbf{x}(t), \mathbf{x}(t-\tau(t)), \delta(t))$$
 (Σ_i)

on intervals $[t_i, t_{i+1})$ when σ is constant and where (Σ_i) operates.

Standing Assumptions

1: There are *k* absolutely continuous functionals V_i , real constants α_i , nonnegative constants β_i , a continuous function *W*, and functions $\chi_i \in \mathcal{K}_{\infty}$ and $\Gamma_i \in \mathcal{K}_{\infty}$ such that

$$\chi_1(|\phi(\mathbf{0})|) \le V_i(t,\phi) \le \chi_2(|\phi|_\infty) \tag{G_g}$$

hold for all $\phi \in C_{in}$, $t \in [0, +\infty)$, and $i \in \{1, 2, \dots, k\}$ and

$$\begin{split} \dot{V}_{\sigma(t_i)}(t) &\leq \alpha_{\sigma(t_i)} V_{\sigma(t_i)}(t, x_t) + \beta_{\sigma(t_i)} \sup_{\ell \in [t - \tau_b, t]} W(x(\ell)) \\ &+ \Gamma_{\sigma(t_i)}(|\delta(t)|) \end{split}$$

for almost all $t \in [t_i, t_{i+1})$ along all trajectories of (Σ_i) for all *i*.

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2: There is a constant $\mu > 1$ such that $W(\phi(0)) \le V_1(t, \phi)$ and $V_i(t, \phi) \le \mu V_i(t, \phi)$ hold for all $\phi \in C_{in}$, all *i* and *j*, and all $t \ge 0$.

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Standing Assumptions and First Theorem

3: There are constants $T \ge \tau_b + T_2$ and $\lambda > 0$ such that

$$\int_{t-T}^{t} \alpha_{\sigma(\ell)} \mathrm{d}\ell \le -\lambda \tag{1}$$

holds for all $t \geq T$.

Standing Assumptions and First Theorem

3: There are constants $T \ge \tau_b + T_2$ and $\lambda > 0$ such that

$$\int_{t-T}^{t} \alpha_{\sigma(\ell)} d\ell \le -\lambda \tag{1}$$

holds for all $t \geq T$.

4: With the choice $\bar{c} = \frac{1}{\mu - 1} (\mu^{L+2} - 1) - L - 1$, we have $\mu^{L+1} e^{-\lambda} + \bar{c} \mu \sup_{t \ge T} \int_{t-T}^{t} \beta_{\sigma(s)} e^{\int_{s}^{t} \alpha_{\sigma(s)} d\ell} ds < 1, \qquad (2)$

where $L = \sup_{t \ge T} \text{Cardinality}\{t_i : t - T \le t_i < t\}$.

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Theorem: Under the preceding assumptions, (Σ) is ISS on \mathbb{R}^n .

For suitable piecewise continuous functions $\overline{w} : \mathbb{R} \to [0, +\infty)$ and *d* that admit constants $T^* > 0$ and $\rho \in (0, 1)$ such that $\overline{w}(t) \le \rho \sup_{\ell \in [t-T^*, t]} \overline{w}(\ell) + d(t)$ holds for all $t \ge 0$, we have

$$\overline{w}(t) \leq \sup_{\ell \in [-T^*,0]} \overline{w}(\ell) e^{\frac{|n(\rho)|}{T^*}t} + \frac{1}{(1-\rho)^2} \sup_{\ell \in [0,t]} |d(\ell)| \text{ for all } t \geq 0.$$
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- Mazenc, F., M. Malisoff, and S.-I. Niculescu. Stability and control design for time-varying systems with time-varying delays using a trajectory based approach. *SIAM Journal on Control and Optimization*, 55(1):533-556, 2017.

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Thank you for your attention!