

Strict Lyapunov Function Constructions under LaSalle Conditions with an Application to Lotka-Volterra Systems

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Motivation

New Constructions

Lotka Volterra System

Conclusions

Background

Robustness Analysis

LaSalle Invariance

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Either way, $\inf_t V(t, x)$ is assumed **proper** and **positive definite**.

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Converse Lyapunov theory guarantees the *existence* of strict Lyapunov functions in many cases.

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Using LaSalle Invariance, we can often use nonstrict Lyapunov functions to prove stability.

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However, explicit strict Lyapunov function *constructions* are often needed in applications.

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ISS is defined using [comparison functions](#).

ISS Motivation-Part 1/3

A function $\alpha : \mathcal{X} \rightarrow [0, \infty)$ is **positive definite** provided $\alpha(0) = 0$ and $\alpha(\zeta) > 0$ for all $\zeta \in \mathcal{X} \setminus \{0\}$.

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A **modulus** with respect to \mathcal{X} is any continuous positive definite function $\alpha : \mathcal{X} \rightarrow [0, \infty)$ such that $\alpha(\zeta) \rightarrow +\infty$ as ζ approaches the boundary of \mathcal{X} , or as $|\zeta| \rightarrow \infty$ with ζ remaining in \mathcal{X} (the latter possibility being ruled out if \mathcal{X} is bounded).

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A continuous function $\beta : [0, \infty) \times [0, \infty) \rightarrow [0, \infty)$ is of class \mathcal{KL} provided $\beta(\cdot, t) \in \mathcal{K}_\infty$ for all $t \geq 0$ and $\beta(s, \cdot)$ is decreasing and asymptotically approaches zero for each $s \geq 0$.

ISS Motivation-Part 2/3

We say that (1) is ISS provided there exist functions $\beta \in \mathcal{KL}$ and $\gamma \in \mathcal{K}_\infty$ and a modulus $\bar{\alpha}$ with respect to \mathcal{X} s.t. for all initial conditions $x(t_0) = x_0 \in \mathcal{X}$ and all disturbances d , the corresponding trajectories $t \mapsto \zeta(t; t_0, x_0, d)$ satisfy

$$|\zeta(t; t_0, x_0, d)| \leq \beta\left(\bar{\alpha}(x_0), t - t_0\right) + \gamma(|d|_\infty) \quad \forall t \geq t_0. \quad (2)$$

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The special case where γ and d are not present is UGAS.

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$$\dot{x} = f(t, x) + g(t, x) \left[K(t, x) - \partial_x V(t, x)g(t, x) + d \right] \quad (4)$$

is ISS with respect to actuator errors d .

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Need $\partial_x V(t, x)g(t, x)$.

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$$\exists N_* > 0 \text{ s.t. } \forall q \in \mathbb{R}^n \setminus \{0\}, \exists i \in [1, N_*] \text{ s.t. } L_f^i V(q) \neq 0. \quad (\text{NDC})$$

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Answer: Yes. (Mazenc-Nesic, IEEE T-AC, 2004).

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Question: Can we transform V into a **strict** Lyapunov function?

Answer: Yes. (Mazenc-Nesic, IEEE T-AC, 2004).

Objective: Find a simpler construction that also applies to t-v systems, and that has a much less restrictive NDC on V .

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Iterated Lie Derivatives Method

Matrosov Method

First Construction

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Let $V \in C^\infty$ be a **nonstrict** Lyapunov function for $\dot{x} = f(t, x)$, $x \in \mathbb{R}^n$, with f and V having period T in t .

First Construction

$a_1 = -\dot{V}$ and $a_{i+1} = -\dot{a}_i$ for $i \geq 1$.

$$A_j(t, x) = \sum_{m=1}^j a_{m+1}(t, x) a_m(t, x).$$

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Theorem 1

Assume \exists constants $\tau \in (0, T]$ and $\ell \in \mathbb{N}$ and a positive definite continuous function ρ such that for all $x \in \mathbb{R}^n$ and all $t \in [0, \tau]$,

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Then we can explicitly determine functions \mathcal{F}_j and \mathcal{G} such that

$$V^\#(t, x) = \sum_{j=1}^{\ell-1} \mathcal{F}_j(V(t, x)) A_j(t, x) + \mathcal{G}(t, V(t, x)) \quad (6)$$

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Significance: The construction can be done locally near the origin, when the assumptions only hold near the origin.

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Significance: The function (6) is a simple weighted sum involving the easily calculated iterated Lie derivatives a_j .

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Significance: Simpler than Mazenc-Nesic-TAC'04, which is limited to time invariant systems under a stronger NDC.

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$$a_1(t, x) + a_2^2(t, x) + a_3^2(t, x) \geq \frac{4 \cos^4(t)}{200(V(x) + 1)} V^2(x).$$

Hence, (5) holds with $\tau = \frac{\pi}{4}$ and $\rho(r) = r^2 / \{200(r + 1)\}$.

Idea of Proof of Thm 1, Part 1/3

Let $\Gamma \in C^1$ be any everywhere positive increasing function s.t.

$$\Gamma(V(t, x)) \geq (\ell + 2)|a_m(t, x)| + 1$$

for all $m \in \{1, \dots, \ell + 1\}$ and all $(t, x) \in [0, \infty) \times \mathbb{R}^n$.

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for all $m \in \{1, \dots, \ell + 1\}$ and all $(t, x) \in [0, \infty) \times \mathbb{R}^n$.

Pick $\omega \in \mathcal{K}_\infty \cap C^1$ and the strictly increasing everywhere positive function $K \in C^1$ such that

$$\rho(r) \geq \frac{\omega(r)}{K(r)} \quad \forall r \geq 0. \quad (8)$$

Idea of Proof of Thm 1, Part 2/3

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Set

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$$k_{\ell-1}(v) = \omega^{2^{\ell-1}}(v) \text{ and } k_p(v) = k_{\ell-1}(v)\Omega^{1-2^{\ell-p-1}}(v) \quad (9)$$

for $1 \leq p \leq \ell - 2$, where $\Omega(v) = \frac{2\tau\omega(v)}{3T(\ell-2)\Gamma^2(v)K(v)}$

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and

$$M_p(t, x) = \sum_{m=1}^p a_{m+1}(t, x)a_m(t, x) + \int_0^{V(t,x)} \Gamma(r)dr. \quad (10)$$

Idea of Proof of Thm 1, Part 2/3

Idea of Proof of Thm 1, Part 2/3

Let k_0 be any C^1 increasing function such that

$$k_0(V(t, x)) + k'_0(V(t, x)) V(t, x) \geq \sum_{\rho=1}^{\ell-1} |k'_\rho(V(t, x))| |M_\rho(t, x)| + 1 \quad (11)$$

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and $q : \mathbb{R} \rightarrow [0, 1]$ be any continuous function with period T s.t. $q(t) = 0$ for all $t \in [\tau, T]$ and $q(t) = 1$ for all $t \in [\frac{\tau}{3}, \frac{2\tau}{3}]$.

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Let G be any C^1 function such that

$$G'(v) \geq T \left| k_{\ell-1}(v) \frac{\omega'(v)K(v) - \omega(v)K'(v)}{K^2(v)} + k'_{\ell-1}(v) \frac{\omega(v)}{K(v)} \right|$$

for all $v \geq 0$.

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$$V^\#(t, x) = V(t, x)S_3(t, x) + \kappa(V(t, x))V(t, x)$$

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and $\kappa \in \mathcal{C}^1$ is any increasing function such that $\kappa(V(t, x)) \geq |\mathcal{S}_3(t, x)| + 1$ everywhere.

Second Construction for $\dot{x} = f(x)$, $x \in \mathcal{X}$

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Assumptions 1

There exist a storage function $V_1 : \mathcal{X} \rightarrow [0, \infty)$; functions h_1, \dots, h_m such that $h_j(0) = 0$ for all j ; everywhere positive functions r_1, \dots, r_m and ρ ; and an integer $N > 0$ for which

$$\nabla V_1(x)f(x) \leq -r_1(x)h_1^2(x) - \dots - r_m(x)h_m^2(x) \quad \forall x \in \mathcal{X} \quad (12)$$

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and

$$\sum_{k=0}^{N-1} \sum_{j=1}^m \left[L_f^k h_j(x) \right]^2 \geq \rho(V_1(x))V_1(x) \quad \forall x \in \mathcal{X}. \quad (13)$$

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$$\text{and} \quad \sum_{k=0}^{N-1} \sum_{j=1}^m \left[L_f^k h_j(x) \right]^2 \geq \rho(V_1(x))V_1(x) \quad \forall x \in \mathcal{X}. \quad (13)$$

Also, $f \in C^\infty(\mathbb{R}^n)$, and V_1 has a positive definite quadratic lower bound in some neighborhood of $0 \in \mathbb{R}^n$.

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One can determine explicit functions $k_\ell, \Omega_\ell \in \mathcal{K}_\infty \cap \mathcal{C}^1$ such that

$$S(x) = \sum_{\ell=1}^N \Omega_\ell \left(k_\ell(V_1(x)) + V_\ell(x) \right) \quad (15)$$

is a strict Lyapunov function on \mathcal{X} satisfying $S(x) \geq V_1(x)$ on \mathcal{X} .

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Significance: New theorem says which functions V_i to pick.

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Significance: Allows any open state space \mathcal{X} containing $0 \in \mathbb{R}^n$.

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Significance: Readily extends to time periodic t-v systems.

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Idea of Proof-Part 1/3

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Find everywhere positive C^1 increasing ϕ_1 and p_1 s.t.

$$\nabla V_i(x)f(x) \leq -\mathcal{N}_i(x) + \phi_1(V_1(x))\sqrt{\mathcal{N}_{i-1}(x)}\sqrt{V_1(x)} \quad (16)$$

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$$\text{and } \mathcal{N}_i(x) = \sum_{l=1}^m \left[L_f^{i-1} h_l(x) \right]^2 \quad \forall i \geq 2.$$

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Find $\underline{\alpha} \in \mathcal{K}_\infty$ so that $V_1(x) \geq \underline{\alpha}(|x|)$ on \mathcal{X} .

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Finally, find a continuous everywhere positive $\tilde{\rho}$ so that

$$\sum_{i=1}^N \mathcal{N}_i(x) \geq \tilde{\rho}(V_1(x)) V_1(x) \quad (18)$$

everywhere.

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$\Omega_N(r) = r$, and $\{\Omega_i\}_{i=1}^{N-1}$ satisfy

$$\Omega'_i(U_i) \geq (N-1)^2 \frac{8\phi_1^2(V_1)}{\tilde{\rho}(V_1)} \sum_{r=1+i}^N \Omega'_r(U_r)^2, \quad (21)$$

with $\Omega'_i : [0, \infty) \rightarrow [1, \infty)$ continuous and increasing for each i .

Statement of Problem

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$$\begin{cases} \dot{\chi} &= \gamma\chi\left(1 - \frac{\chi}{L}\right) - a\chi\zeta \\ \dot{\zeta} &= \beta\chi\zeta - \Delta\zeta \end{cases} \quad (22)$$

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Assume $\alpha > d$. **Want a global strict Lyapunov function for (23).**

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Nonstrict Lyapunov decay condition:

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Along the trajectories of the L-V error dynamics,

$$\dot{S} \leq -\frac{1}{4} \left[\tilde{x}^2 + \{(\tilde{x} + \alpha\tilde{y})(\tilde{x} + x_*)\}^2 \right]. \quad (27)$$

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For example, their time derivatives are frequently bounded above by **negative definite quadratic functions** of the state.

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