

# Lyapunov Functions under LaSalle Conditions with an Application to Lotka-Volterra Systems

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Motivation

New Constructions

Lotka Volterra System

Conclusions

Background

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Converse Lyapunov theory guarantees the *existence* of strict Lyapunov functions in many cases.



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Using LaSalle Invariance, we can often use nonstrict Lyapunov functions to prove stability.

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However, explicit strict Lyapunov function *constructions* are often needed in applications.

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Iterated Lie Derivatives Method

Matrosov Method

# First Construction

## First Construction

Let  $V \in C^\infty$  be a **nonstrict** Lyapunov function for  $\dot{x} = f(t, x)$ ,  $x \in \mathbb{R}^n$ , with  $f$  and  $V$  having period  $T$  in  $t$ .

# First Construction

$a_1 = -\dot{V}$  and  $a_{i+1} = -\dot{a}_i$  for  $i \geq 1$ .

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Assume  $\exists$  constants  $\tau \in (0, T]$  and  $\ell \in \mathbb{N}$  and a positive definite continuous function  $\rho$  such that for all  $x \in \mathbb{R}^n$  and all  $t \in [0, \tau]$ ,

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Then we can explicitly determine functions  $\mathcal{F}_j$  and  $\mathcal{G}$  such that

$$V^\#(t, x) = \sum_{j=1}^{\ell-1} \mathcal{F}_j(V(t, x)) A_j(t, x) + \mathcal{G}(t, V(t, x)) \quad (2)$$

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**Significance:** The construction can be done locally near the origin, when the assumptions only hold near the origin.

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**Significance:** The function (2) is a simple weighted sum involving the easily calculated iterated Lie derivatives  $a_j$ .

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**Significance:** Simpler than Mazenc-Nesic-TAC'04, which is limited to time invariant systems under a stronger NDC.

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### Assumptions 1

*There exist a storage function  $V_1 : \mathcal{X} \rightarrow [0, \infty)$ ; functions  $h_1, \dots, h_m$  such that  $h_j(0) = 0$  for all  $j$ ; everywhere positive functions  $r_1, \dots, r_m$  and  $\rho$ ; and an integer  $N > 0$  for which*

$$\nabla V_1(x)f(x) \leq -r_1(x)h_1^2(x) - \dots - r_m(x)h_m^2(x) \quad \forall x \in \mathcal{X} \quad (3)$$



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and

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*Also,  $f \in C^\infty(\mathbb{R}^n)$ , and  $V_1$  has a positive definite quadratic lower bound in some neighborhood of  $0 \in \mathbb{R}^n$ .*

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One can determine explicit functions  $k_\ell, \Omega_\ell \in \mathcal{K}_\infty \cap \mathcal{C}^1$  such that

$$S(x) = \sum_{\ell=1}^N \Omega_\ell \left( k_\ell(V_1(x)) + V_\ell(x) \right) \quad (6)$$

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**Significance:** New theorem says which functions  $V_i$  to pick.



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**Significance:** Allows any open state space  $\mathcal{X}$  containing  $0 \in \mathbb{R}^n$ .

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**Significance:** Readily extends to t-v systems.

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$\zeta$  = predator.  $\chi$  = prey.

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Assume  $\alpha > d$ . **Want a global strict Lyapunov function for (8).**

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Auxiliary function from theorem:

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Auxiliary function from theorem:  $V_2(\tilde{x}, \tilde{y}) = \tilde{x}[\tilde{x} + \alpha\tilde{y}](\tilde{x} + x_*)$ .

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 S(\tilde{x}, \tilde{y}) = & V_2(\tilde{x}, \tilde{y}) + \int_0^{V_1(\tilde{x}, \tilde{y})} \phi_1(r) dr \\
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Along the trajectories of the L-V error dynamics,

$$\dot{S} \leq -\frac{1}{4} \left[ \tilde{x}^2 + \{(\tilde{x} + \alpha\tilde{y})(\tilde{x} + x_*)\}^2 \right]. \quad (12)$$

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Our strict Lyapunov function for the Lotka-Volterra model leads to an **ISS** robustness analysis under uncertain death rates.

## Summary and Extensions (cont'd)

Mazenc, F., and M. Malisoff, “Strict Lyapunov Function Constructions Under LaSalle Conditions with an Application to Lotka-Volterra Systems,” *IEEE Transactions on Automatic Control*, provisionally accepted as full paper.

## Summary and Extensions (cont'd)

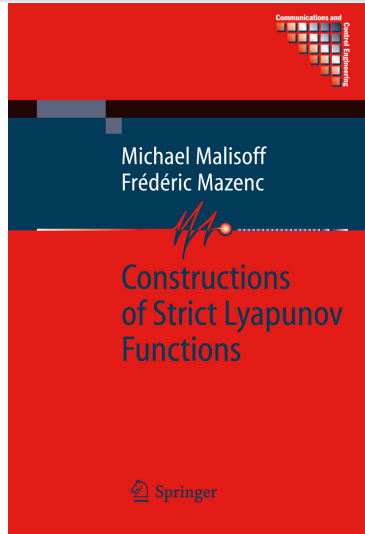
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# Further Reading

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Hence, (1) holds with  $\tau = \frac{\pi}{4}$  and  $\rho(r) = r^2 / \{200(r + 1)\}$ .

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$\Omega_N(r) = r$ , and  $\{\Omega_i\}_{i=1}^{N-1}$  satisfy

$$\Omega'_i(U_i) \geq (N-1)^2 \frac{8\phi_1^2(V_1)}{\tilde{\rho}(V_1)} \sum_{r=1+i}^N \Omega'_r(U_r)^2, \quad (16)$$

with  $\Omega'_i : [0, \infty) \rightarrow [1, \infty)$  continuous and increasing for each  $i$ .