

3 Linear maps

We have all seen linear maps before. In fact, most of the maps that you have been using in calculus are linear.

The integral To integrate the function $x^2 + 3x - \cos x$ over the interval $[a, b]$ we first find the antiderivative of x^2 , i.e. $\frac{1}{3}x^3$, then the antiderivative of x , i.e., $\frac{1}{2}x^2$, and then multiply this function by 3 to get $\frac{3}{2}x^2$. Finally we find the antiderivative of $\cos(x)$, i.e., $\sin(x)$ and then multiply $\sin(x)$ by -1 . To finish the problem we insert the endpoints. Thus

$$\begin{aligned} \int_{-1}^1 x^2 + 3x - \cos x \, dx &= \int_{-1}^1 x^2 \, dx + 3 \int_{-1}^1 x \, dx - \int_{-1}^1 \cos x \, dx \\ &= \left[\frac{1}{3} x^3 \right]_{-1}^1 + \left[\frac{3}{2} x^2 \right]_{-1}^1 - \left[\sin x \right]_{-1}^1 \\ &= \frac{2}{3} - \sin(1) + \sin(-1) \\ &= \frac{2}{3} - 2\sin(1). \end{aligned}$$

What we have used is the fact that the integral is a linear map $C^1([a, b]) \rightarrow C([a, b])$

$$\int_a^b r f(t) + s g(t) \, dt = r \int_a^b f(t) \, dt + s \int_a^b g(t) \, dt.$$

Differentiation Another example is the differentiation $Df = f'$.

To differentiate the function $f(x) = x^4 - 3x + e^x - \cos(x)$ we first differentiate each of the function and then add:

$$\begin{aligned} D(x^4 - 3x + e^x - \cos(x)) &= Dx^4 - 3Dx + De^x - D\cos(x) \\ &= 4x^3 - 3 + e^x + \sin(x). \end{aligned}$$

Definition Let V and W be two vector spaces. A map $T: V \rightarrow W$ is said to be linear if for all $v, u \in V$ and all $r, s \in \mathbb{R}$ we have

$$T(rv + su) = rT(v) + sT(u).$$

Remark This can also be written by using two equations

$$\begin{aligned} T(u+v) &= T(u) + T(v) \quad [\text{additive}] \\ T(rv) &= rT(v). \end{aligned}$$

Lemma Suppose that $T: V \rightarrow W$ is linear. Then $T(\vec{0}) = \vec{0}$.

Proof: We can write $\vec{0} = 0 \cdot v$, where v is any vector in V .
But then $T(\vec{0}) = T(0 \cdot v) = 0 \cdot T(v) = \vec{0}$ \square

Example Let us find all the linear maps from \mathbb{R}^2 to \mathbb{R}^2 .
An arbitrary vector $(x_1, x_2) \in \mathbb{R}^2$ can be written as

$$(x_1, x_2) = x_1(1, 0) + x_2(0, 1)$$

Hence $T(x_1, x_2) = x_1 T(1, 0) + x_2 T(0, 1)$. Write

$$T(1, 0) = (a_{11}, a_{12}), \quad T(0, 1) = (a_{21}, a_{22}) \quad \text{where } a_{ij} \in \mathbb{R}$$

Then

$$\begin{aligned} T(x_1, x_2) &= x_1(a_{11}, a_{12}) + x_2(a_{21}, a_{22}) \\ &= (x_1 a_{11} + x_2 a_{21}, x_1 a_{12} + x_2 a_{22}). \end{aligned}$$

Thus all the information about T is given by the matrix

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}.$$

Example: Next let us find all the linear maps $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$
 As before we write

$$(x_1, x_2, x_3) = x_1(1, 0, 0) + x_2(0, 1, 0) + x_3(0, 0, 1)$$

$$T(1, 0, 0) = (a_{11}, a_{12}, a_{13})$$

$$T(0, 1, 0) = (a_{21}, a_{22}, a_{23})$$

$$T(0, 0, 1) = (a_{31}, a_{32}, a_{33}).$$

Then

$$T(x_1, x_2, x_3) = x_1(a_{11}, a_{12}, a_{13}) + x_2(a_{21}, a_{22}, a_{23}) + x_3(a_{31}, a_{32}, a_{33})$$

$$= (x_1 a_{11} + x_2 a_{21} + x_3 a_{31}, x_1 a_{12} + x_2 a_{22} + x_3 a_{32}, x_1 a_{13} + x_2 a_{23} + x_3 a_{33})$$

$$= (x_1, x_2, x_3) \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

Example All the linear maps $T: \mathbb{R}^3 \rightarrow \mathbb{R}$.

Notice, that \mathbb{R} is also a vector space, so we can consider all the linear maps $T: \mathbb{R}^n \rightarrow \mathbb{R}$. We have

$$\begin{aligned} T(x_1, x_2, \dots, x_n) &= x_1 T(1, 0, \dots, 0) + x_2 T(0, 1, 0, \dots, 0) + \dots + x_n T(0, \dots, 0, 1) \\ &= x_1 a_1 + x_2 a_2 + \dots + x_n a_n \end{aligned}$$

where $T(1, 0, \dots, 0) = a_1$, $a_2 = T(0, 1, 0, \dots, 0)$, \dots , $a_n = T(0, \dots, 0, 1)$
 are real numbers.

Theorem A map $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is linear if and only if there exists numbers a_{ij} , $i=1, \dots, m$, $j=1, \dots, n$, such that

$$T(x_1, \dots, x_n) = (x_1 a_{11} + x_2 a_{21} + \dots + x_n a_{n1}, \dots, x_1 a_{1m} + x_2 a_{2m} + \dots + x_n a_{nm})$$

This can also be written as

$$T(x_1, \dots, x_n) = \left(\sum_{i=1}^m x_i a_{i1}, \sum_{i=1}^m x_i a_{i2}, \dots, \sum_{i=1}^m x_i a_{im} \right)$$

as by using matrix multiplication

$$T(x_1, \dots, x_n) = (x_1, \dots, x_n) \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1m} \\ a_{21} & a_{22} & & \vdots \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & & a_{nm} \end{bmatrix}$$

Example The map $T(x, y, z) = (2x + 3xy, z + y)$ is not linear because of the factor xy . Notice that

add few examples.

but $T(1, 1, 0) = (5, 0)$
and $T(2(1, 1, 0)) = T(2, 2, 0) = (16, 0)$
 $2T(1, 1, 0) = (10, 0) \neq (16, 0)$.

Examples

Evaluate the given linear maps at the given point

- $T(x, y) = (3x + y, 3y)$, $(x, y) = (1, -1)$
 $T(1, -1) = (3 \cdot 1 + (-1), 3(-1)) = (2, -1)$
- $T(x, y, z) = (2x - y + 3z, 2x + z)$, $(x, y, z) = (2, -1, 1)$
 $T(2, -1, 1) = (4 + 1 + 3, 4 + 1) = (8, 5)$.

- $T: \mathbb{R}^3 \rightarrow \mathbb{R}, T(x, y, z) = 2x - 5y + z$, $(x, y, z) = (2, 1, 1)$
 $T(2, 1, 1) = 4 - 5 + 1 = 0$.

Take some example involving differentiation and integration

$$D(3x^2 + 4x - 1) = 6x + 4$$

$$\int_1^2 x^2 - e^x dx = \left[\frac{1}{3}x^3 - e^x \right]_1^2 = \frac{8}{3} - e^2 - \frac{1}{3} + e = \frac{7}{3} - e^2 + e$$

Definition Let V and W be two vector spaces and $T: V \rightarrow W$ a linear map.

(1) The set $\ker(T) = \{v \in V: T(v) = 0\}$ is called the kernel (or nullspace) of T .

(2) The set $\{w \in W: \text{There exists a } v \in V: T(v) = w\} = T(\mathbb{V}) = \text{Im}(T)$ is called the image of T .

Remark Notice that $\ker(T) \subseteq V$ and $\text{Im}(T) \subseteq W$

Theorem The kernel of T is a vector space.

Proof. Let $u, v \in \ker(T)$ and $r, s \in \mathbb{R}$. We have to show that $ru + sv \in \ker(T)$. Now $u, v \in \ker(T)$ if and only if $T(u) = T(v) = 0$. Hence

$$\begin{aligned} T(ru + sv) &= rT(u) + sT(v) && (T \text{ is linear}) \\ &= r \cdot 0 + s \cdot 0 && (u, v \in \ker(T)). \\ &= 0 \end{aligned}$$

This shows that $ru + sv \in \ker(T)$ \square

Remark Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the map $T(x, y) = (x^2 + y, x + y)$

Then $T(1, -1) = (1 - 1, 1 - 1) = (0, 0)$. But

$$T(2(1, -1)) = T(2, -2) = (4 - 2, 2 - 2) = (2, 0) \neq (0, 0).$$

So if T is not linear, then the set $\{v \in V: T(v) = 0\}$ is in general not a vector space.

Example Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}$ be the map $T(x, y) = 2x - y$.

Describe the kernel of T .

Solution (x, y) is in the kernel of T if and only if $T(x, y) = 2x - y = 0$. Hence $y = 2x$. Thus, the kernel of T is a line through $(0, 0)$ with slope 2.

Example Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$, $T(x, y, z) = (2x - 3y + z, x + 2y - z)$

Describe the kernel of T .

Solution: We have that $(x, y, z) \in \ker(T)$ if and only if

$$\begin{aligned} 2x - 3y + z &= 0 & \text{and} \\ x + 2y - z &= 0 \end{aligned}$$

The first equation describes a plane through $(0, 0, 0)$ with normal vector $(2, -3, 1)$. The second equation describes a plane with normal vector $(1, 2, -1)$ (and containing $(0, 0, 0)$). The normal vectors are not parallel and therefore the planes are different. It follows, that the intersection is a line. Let us describe this line. Adding the equations we get

$$3x - y = 0$$

or $y = 3x$. Plugging this into the second equation we get:

$$0 = x + 2(3x) - z = 7x - z$$

or

$$z = 7x$$

Hence the line is given by $x \cdot (1, 3, 7)$.

Theorem Let V and W be vector spaces, $T: V \rightarrow W$ linear. Then

$$\text{Im}(T) \subseteq W$$

is a vector space.

Proof. Let $w_1, w_2 \in \text{Im}(T)$. Then we can find $u_1, u_2 \in V$ such that $T(u_1) = w_1$, $T(u_2) = w_2$. Let $r, s \in \mathbb{R}$. Then

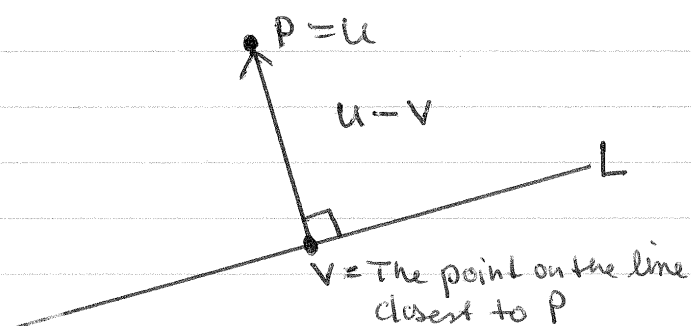
$$\begin{aligned} rw_1 + sw_2 &= rT(u_1) + sT(u_2) \\ &= T(ru_1 + su_2) \in \text{Im}(T) \quad \square \end{aligned}$$

(add examples how to determine $\text{Im}(T)$ in special cases?)

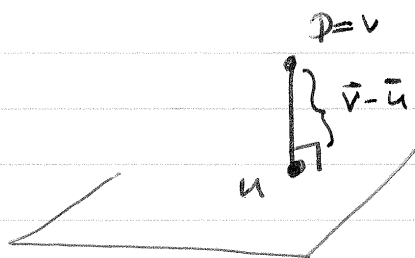
§ 4 Inner product

Let us start with the following problem. Given a point $P \in \mathbb{R}^2$ and a line $L \subseteq \mathbb{R}^2$. How can we find the point on the line closest to P .

Answer: Draw a line segment starting at P and meeting the line in a right angle. Then the point of intersection is the point on the line closest to P .



Let us now take a plane $L \subset \mathbb{R}^3$ and a point outside the line. How can we find the point $\vec{u} \in L$ closest to P . The answer is the same as before, go from P so that we meet the plane in a right angle.



In both examples we need two things:

- A: We have to be able to say what the length of a vector is
- B: Say what a right angle is.

Both of those things can be done by using the dot-product or inner product in \mathbb{R}^n .

Definition Let $(x_1, \dots, x_n), (y_1, \dots, y_n) \in \mathbb{R}^n$. Then the dot- or inner-product of those vectors is given by the numbers:

$$((x_1, \dots, x_n), (y_1, \dots, y_n)) = x_1 y_1 + x_2 y_2 + \dots + x_n y_n.$$

The norm (or length) of the vector $\vec{u} = (x_1, \dots, x_n) \in \mathbb{R}^n$ is the non-negative number

$$\|u\| = \sqrt{(u, u)} = \sqrt{x_1^2 + \dots + x_n^2}$$

Example a) $((1, 2, -3), (1, 1, 1)) = 1 + 2 - 3 = 0$

b) $((1, -2, 1), (2, -1, 3)) = 2 + 2 + 3 = 7$

Because $|x_1 y_1 + \dots + x_n y_n| \leq \sqrt{x_1^2 + \dots + x_n^2} \sqrt{y_1^2 + \dots + y_n^2}$

or

$$|(u, v)| \leq \|u\| \cdot \|v\|$$

we have that (for $u, v \neq 0$)

$$-1 \leq \frac{(u, v)}{\|u\| \cdot \|v\|} \leq 1$$

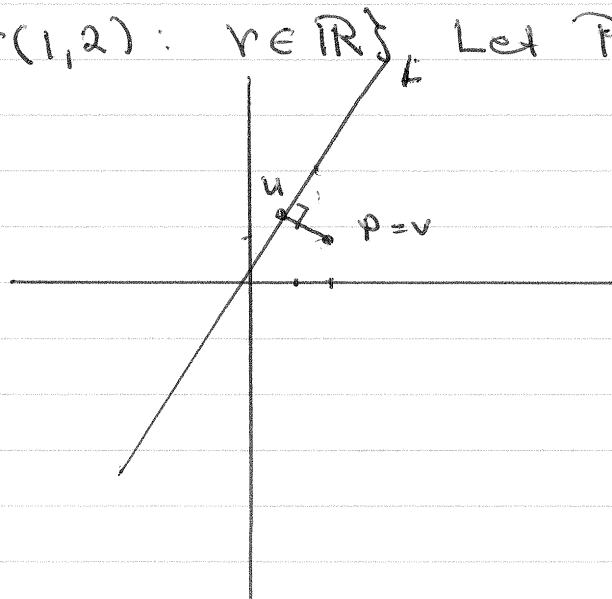
Hence we can define

$$\cos(\angle(u, v)) = \frac{(u, v)}{\|u\| \cdot \|v\|}$$

in particular $u \perp v$ (u perpendicular to v) if and only if $(u, v) = 0$.

Example Let L be the line in \mathbb{R}^2 given by $y=2x$.

Thus $L = \{r(1,2) : r \in \mathbb{R}\}$. Let $P = (2,1)$



what is the point on L closest to P .

Answer Because $u \in L$, we can write $\vec{u} = (r, 2r)$. Furthermore $\vec{v} - \vec{u} = (2-r, 1-2r)$ is perpendicular to L . Hence

$$0 = ((1,2), (2-r, 1-2r)) = 2-r+2-4r = 4-5r$$

Hence $r = \frac{4}{5}$ and

$$\vec{u} = \left(\frac{4}{5}, \frac{8}{5}\right).$$

What is the distance of P from the line?

Answer: The length of the vector $\vec{v} - \vec{u}$, $\|\vec{v} - \vec{u}\|$.

First we have to find out what $\vec{v} - \vec{u}$ is. We have done almost all the work:

$$\vec{v} - \vec{u} = (2,1) - \left(\frac{4}{5}, \frac{8}{5}\right) = \left(\frac{6}{5}, -\frac{3}{5}\right)$$

The distance is therefore

$$\sqrt{\frac{36}{25} + \frac{9}{25}} = \frac{1}{5} \sqrt{45} = \frac{3}{\sqrt{5}}$$

① To be able to define the norm, we used that

positivity: $(u, u) \geq 0$

② Zero length: All non-zero vectors should have a non-zero length. Thus $(u, u) = 0$ only if $u = 0$.

③ Linearity: If the vector $v \in \mathbb{R}^n$ is fixed, then the map $u \mapsto (u, v)$ from \mathbb{R}^n to \mathbb{R} is linear. That is

$$(ru + sv, v) = r(u, v) + s(w, v)$$

④ Symmetric: for all $u, v \in \mathbb{R}^n$ we have

$$(u, v) = (v, u)$$

We use this to define an inner product on arbitrary vector space V

Definition Let V be a vector space.

An inner product on V is a map $(\cdot, \cdot) : V \times V \rightarrow \mathbb{R}$ satisfying the following properties:

(1) positivity: We have for all $u \in V$: $(u, u) \geq 0$

(2) $(u, u) = 0$ only if $u = 0$

(3) linearity If $w \in V$ is fixed, then the map

$V \rightarrow \mathbb{R}, v \mapsto (v, w)$, is linear.

(4) Symmetric If $v, w \in V$, then $(v, w) = (w, v)$.

Lemma $(u, rv + sw) = r(u, v) + s(u, w)$.

Proof. (in class)

Def. We say that u and v are perpendicular if $(u, v) = 0$.

Definition If (\cdot, \cdot) is an inner product on the vector space V , then the norm of a vector $u \in V$ is given by

$$\|u\| := \sqrt{(u, u)}$$

The norm satisfies the following properties:

(1) $\|u\| \geq 0$ and $\|u\| = 0$ only if $u = 0$.

(2) $\|ru\| = |r| \cdot \|u\|$.

Proof. We have $\|ru\| = \sqrt{(ru, ru)}$

$$= \sqrt{r(u, ru)}$$

$$= \sqrt{r^2(u, u)}$$

$$= |r| \sqrt{(u, u)} = |r| \cdot \|u\|.$$

Ex: Let $a < b$ and $I = [a, b]$, $V = PC([a, b])$. Define

$$(f, g) := \int_a^b f(t)g(t) dt.$$

Then (\cdot, \cdot) is an inner product on V

Proof: Let $r, s \in \mathbb{R}$, $f, g, h \in V$. Then:

$$(f, f) = \int_a^b f(t)^2 dt.$$

As $f(t)^2 \geq 0$ it follows, that

$$\int_a^b f(t)^2 dt \geq 0$$

(2) If $(f, f) = 0$, then $f(t)^2 = 0$ for all t , or $f = 0$.

$$\begin{aligned} (3) \int_a^b (rf + sg)(t)h(t) dt &= \int_a^b rf(t)h(t) + sg(t)h(t) dt \\ &= r \int_a^b f(t)h(t) dt + s \int_a^b g(t)h(t) dt \\ &= r(f, h) + s(g, h) \end{aligned}$$

Hence linear in the first factor.

(4) As $f(t)g(t) = g(t)f(t)$ it follows that $(f, g) = (g, f)$

Notice, that the norm is

$$\|f\| = \sqrt{\int_a^b f(t)^2 dt}$$

Example: Let $a=0, b=1$.

• $f(t) = t^2, g(t) = t - 3t^2$. Then

$$\begin{aligned} (f, g) &= \int_0^1 t^2(t - 3t^2) dt = \int_0^1 t^3 - 3t^4 dt \\ &= \frac{1}{4} - \frac{3}{5} = \frac{5-12}{20} = -\frac{7}{20} \end{aligned}$$

$$\|f\| = \sqrt{\int_0^1 t^4} = \frac{1}{\sqrt{5}}$$

$$\begin{aligned} \|g\| &= \sqrt{\int_0^1 (t - 3t^2) \cdot (t - 3t^2) dt} \\ &= \sqrt{\int_0^1 t^2 - 6t^3 + 9t^4 dt} \\ &= \sqrt{\frac{1}{3} - 3 \cdot \frac{3}{2} + \frac{9}{5}} = \sqrt{\frac{19}{30}} \end{aligned}$$

- $f(x) = \cos(2\pi t)$, $g(x) = \sin(2\pi t)$. Then

$$\begin{aligned} (f, g) &= \int_0^1 \cos(2\pi t) \sin(2\pi t) dt & u &= \sin(2\pi t) \\ &= \frac{1}{4\pi} [\sin(2\pi t)]^2 \Big|_0^1 = 0 & du &= 2\pi \cos(2\pi t) \\ & & \frac{1}{2\pi} \int u du &= \frac{1}{4\pi} u^2 + C \end{aligned}$$

So $\cos(2\pi t)$ is perpendicular to $\sin(2\pi t)$ on the interval $[0, 1]$.

- $f(t) = \chi_{[0, 1/2)} - \chi_{[1/2, 1)}$, $g(t) = \chi_{[0, 1]}$

$$\begin{aligned} \text{Then } (f, g) &= \int_0^1 (\chi_{[0, 1/2)}(t) - \chi_{[1/2, 1)}(t)) \chi_{[0, 1]}(t) dt \\ &= \int_0^{1/2} \chi_{[0, 1/2)}(t) dt - \int_{1/2}^1 \chi_{[1/2, 1)}(t) dt \\ &= \int_0^{1/2} dt - \int_{1/2}^1 dt = \frac{1}{2} - \frac{1}{2} = 0 \end{aligned}$$

Show that $\|f\| = \|g\| = 1$.

— · —

Problem: Find a polynomial $f(t) = a + bt$, that is perpendicular to the vector (polynomial) $g(t) = 1 - t$.

Answer: We are looking for numbers a and b s.t.

$$\begin{aligned} 0 &= (f, g) = \int_0^1 (a + bt)(1 - t) dt = \\ &= \int_0^1 a + bt - at - bt^2 dt \\ &= a + \frac{b}{2} - \frac{a}{2} - \frac{b}{3} = \dots \quad \frac{a}{2} + \frac{b}{6} \end{aligned}$$

Thus $3a + b = 0$. So we can take $f(t) = 1 - 3t$

We state now two important facts about an inner product on a vector space V . Recall, that in \mathbb{R}^2

$$\cos(\theta) = \frac{(u, v)}{\|u\| \cdot \|v\|}$$

where \vec{u}, \vec{v} are two non-zero vectors in \mathbb{R}^2 and θ is the angle between \vec{u} and \vec{v} . In particular, because $-1 \leq \cos \theta \leq 1$, we must have

$$|(u, v)| \leq \|u\| \cdot \|v\|$$

We will now show, that this comes from the positivity and linearity of the inner product.

Theorem Let V be a vector space with inner product (\cdot, \cdot) .

Then

$$|(u, v)| \leq \|u\| \cdot \|v\|$$

for all $\vec{u}, \vec{v} \in V$.

Proof. We can assume, that $\vec{u}, \vec{v} \neq 0$, because otherwise both the LHS and the RHS will be zero. By the positivity of the inner product we get:

$$\begin{aligned}
0 &\leq \left(\vec{v} - \frac{(\vec{v}, \vec{u})}{\|\vec{u}\|^2} \vec{u}, \vec{v} - \frac{(\vec{v}, \vec{u})}{\|\vec{u}\|^2} \vec{u} \right) \quad [\text{positivity}] \\
&= (\vec{v}, \vec{v}) - \frac{(\vec{v}, \vec{u})}{\|\vec{u}\|^2} (\vec{u}, \vec{v}) - \frac{(\vec{v}, \vec{u})}{\|\vec{u}\|^2} (\vec{v}, \vec{u}) \\
&\quad + \frac{(\vec{v}, \vec{u})^2}{\|\vec{u}\|^4} (\vec{u}, \vec{u}) \quad \left. \vphantom{\frac{(\vec{v}, \vec{u})}{\|\vec{u}\|^2}} \right\} [\text{linearity}] \\
(\vec{u}, v) &= (v, u), (\vec{v}, \vec{v}) = \|\vec{v}\|^2 \\
&\stackrel{\downarrow}{=} \|\vec{v}\|^2 - 2 \frac{(\vec{u}, \vec{v})^2}{\|\vec{u}\|^2} + \frac{(\vec{v}, \vec{u})^2}{\|\vec{u}\|^2} \quad \left[\begin{array}{l} \text{Symmetry} \\ \text{definition of the norm} \end{array} \right] \\
&= \|\vec{v}\|^2 - \frac{(\vec{u}, \vec{v})^2}{\|\vec{u}\|^2} .
\end{aligned}$$

Thus

$$\frac{(\vec{v}, \vec{u})^2}{\|\vec{u}\|^2} \leq \|\vec{v}\|^2$$

or

$$|(\vec{v}, \vec{u})| \leq \|\vec{v}\| \cdot \|\vec{u}\|$$

□

Notice, that

$$0 = \left(\vec{v} - \frac{(\vec{v}, \vec{u})}{\|\vec{u}\|^2} \vec{u}, \vec{v} - \frac{(\vec{v}, \vec{u})}{\|\vec{u}\|^2} \vec{u} \right)$$

only if

$$\vec{v} - \frac{(\vec{v}, \vec{u})}{\|\vec{u}\|^2} \vec{u} = 0$$

or

$$\vec{v} = \frac{(\vec{v}, \vec{u})}{\|\vec{u}\|^2} \vec{u}.$$

Thus \vec{v} and \vec{u} have to be on the same line through 0 .

We can therefore conclude:

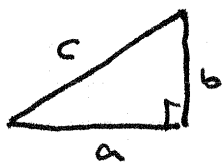
Lemma We have

$$|(\vec{u}, \vec{v})| = \|\vec{u}\| \cdot \|\vec{v}\|$$

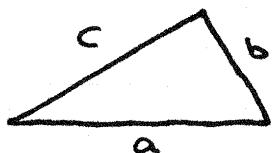
if and only if \vec{u} and \vec{v} are on the same line through 0 ,

The next statement is a generalization of

Pythagoras' Theorem



$$c^2 = a^2 + b^2$$



$$c < a + b$$

Theorem Let V be a vector space with inner product (\cdot, \cdot) .

Then

$$\|\vec{u} + \vec{v}\| \leq \|\vec{u}\| + \|\vec{v}\|.$$

Furthermore $\|\vec{u} + \vec{v}\|^2 = \|\vec{u}\|^2 + \|\vec{v}\|^2$ if and only if $(\vec{u}, \vec{v}) = 0$.

Proof

$$\|\vec{u} + \vec{v}\|^2 = (\vec{u} + \vec{v}, \vec{u} + \vec{v})$$

$$= (\vec{u}, \vec{u}) + 2(\vec{u}, \vec{v}) + (\vec{v}, \vec{v}) \quad (*)$$

$$\leq \|\vec{u}\|^2 + 2\|\vec{u}\| \cdot \|\vec{v}\| + \|\vec{v}\|^2 \quad [\text{using the last theorem}]$$

$$= (\|\vec{u}\| + \|\vec{v}\|)^2$$

If $(\vec{u}, \vec{v}) = 0$, then $(*)$ reads

$$\|\vec{u} + \vec{v}\|^2 = \|\vec{u}\|^2 + \|\vec{v}\|^2.$$

On the other hand if $\|\vec{u} + \vec{v}\|^2 = \|\vec{u}\|^2 + \|\vec{v}\|^2$, we

see from $(*)$

$$\|\vec{u} + \vec{v}\|^2 = \|\vec{u}\|^2 + 2(\vec{u}, \vec{v}) + \|\vec{v}\|^2 = \|\vec{u}\|^2 + \|\vec{v}\|^2 + 2(\vec{u}, \vec{v}).$$

$$\text{that } 2(\vec{u}, \vec{v}) = 0$$

Examples

(a) $\vec{u} = (1, 2, -1)$, $\vec{v} = (0, 2, 4)$. Then

$$(\vec{u}, \vec{v}) = 4 - 4 = 0.$$

$$\|\vec{u}\|^2 = 1 + 4 + 1 = 6, \quad \|\vec{v}\|^2 = 4 + 16 = 20.$$

$$\vec{u} + \vec{v} = (1, 4, 3) \quad \text{and}$$

$$\|\vec{u} + \vec{v}\|^2 = 1 + 16 + 9 = 26 = 6 + 20.$$

Math 2025, Exercices: Inner products and norms

Recall that an inner product on \mathbb{R}^n is given by $((x_1, \dots, x_n), (y_1, \dots, y_n)) = x_1y_1 + \dots + x_ny_n$. The length or norm of a vector $\vec{x} = (x_1, \dots, x_n)$ is the real number

$$\|(x_1, \dots, x_n)\| = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2} = \sqrt{(\vec{x}, \vec{x})}$$

Inner product on functions on $[a, b]$ (piecewise continuous, continuous, etc.) is given by $(f, g) = \int_a^b f(t)g(t) dt$. The norm is

$$\|f\| = \sqrt{(f, f)} = \sqrt{\int_a^b f(t)^2 dt}.$$

Recall, that if A is a subset of \mathbb{R}^n then the indicator function of A is the function $\chi_A : \mathbb{R}^n \rightarrow \mathbb{R}^n$ given by

$$\chi_A(t) = \begin{cases} 1 & \text{if } t \in A \\ 0 & \text{if } t \notin A \end{cases}$$

1) Evaluate the inner product of the following vectors in \mathbb{R}^n :

a) $((1, 0, -3), (2, 1, 3)) =$

b) $((2, 2, -1, -1), (1, 1, 2, 2)) =$

c) $((1, 2, 3, 4, 5), (0, 2, 5, 3, 6)) =$

2) Find the norm of the following vectors:

a) $\|(1, 3, 1)\| =$

b) $\|(-1, 2, 3, 5)\| =$

Two non-zero vectors are called perpendicular or orthogonal if the inner product $(\vec{x}, \vec{y}) = 0$.

3) Which of the following vectors are perpendicular to each other?

a) $(1, 0), (0, -2)$

b) $(1, 0, 1), (-1, 2, 1)$

c) $(2, -1, 0), (1, 1, 3)$

d) $(1, -2, 1, 2)$, and $(1, -1, 1, -2)$.

4) Find the inner product of the following function in $C([0, 1])$ (thus $a = 0$ and $b = 1$).

a) $(1, t)$

b) $(\cos(t), t) =$

c) $(t, t^2 + 1) =$

d) $(t, e^{t^2}) =$

e) $(\cos(4\pi t), \sin(4\pi t)) =$

f) $(t, e^t) =$

5) Find the norm of the following functions:

a) $\|\cos(t)\| =$

b) $\|1 + t\| =$

c) $\|\frac{1}{\sqrt{1+t}}\| =$

d) $\|e^t\| =$

e) $\|\frac{\sqrt{t}}{1+t^2}\| =$

6) Which of the following functions are orthogonal on the interval $[0, 1]$?

a) t and $1 - \frac{1}{6}t$;

b) 1 (the constant function that maps all t into the number 1) and $2 - 2t - 3t^2$.

c) $2\chi_{[0,1)}$ and $\chi_{[0,1/2)} - \chi_{[1/2,1)}$,

d) $\chi_{[0,1)}$ and $\chi_{[0,1/4)} - \chi_{[1/4,1/2)}$.

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