

local existence and uniqueness theory for the nonlinear initial-value problem

$$(IVP) \begin{cases} \dot{x} = F(x) \\ x(t_0) = x_0 \end{cases}$$

Given positive numbers  $a$  and  $\rho$ , solutions of this IVP will be considered in the space of continuous functions  $x: J_a \rightarrow B_\rho$ , in which

$$J_a = t_0 + (-a, a)$$

$$B_\rho = \{y \in \mathbb{R}^n : |y - x_0| \leq \rho\}$$

This set will be denoted by  $X$ :

$$X = \{x: J_a \rightarrow B_\rho : x \text{ is continuous}\}$$

when endowed with the following notion of distance,

$$\|x_1 - x_2\|_{\text{sup}} = \sup_{t \in J_a} |x_1(t) - x_2(t)|,$$

$X$  becomes a complete metric space. You can prove this by the following steps (exercise):

- (1) The linear space  $BC(J_a, \mathbb{R}^n)$  of bounded continuous functions from  $J_a$  to  $\mathbb{R}^n$ , with the sup norm  $\|x\|_{\text{sup}} = \sup_{t \in J_a} |x(t)|$  is a Banach space (closed normed vector space).
- (2)  $\|x - y\|_{\text{sup}}$  defines a metric on any subset of  $BC$ .
- (3)  $B_\rho$  being closed (and bounded) makes  $X$  complete in this metric.

2

Defn For a subset  $S \subset \mathbb{R}^n$ , a function  $F: S \rightarrow \mathbb{R}^n$  is Lipschitz with Lipschitz constant  $K > 0$  if  $\forall y_1, y_2 \in S, |F(y_1) - F(y_2)| \leq K|y_1 - y_2|$ .

Exercise If  $F: S \rightarrow \mathbb{R}^n$  is Lipschitz, then  $F$  is continuous. If  $S$  is bounded and  $F: S \rightarrow \mathbb{R}^n$  is Lipschitz, then  $F$  is bounded.

Theorem Let  $F: B_p \rightarrow \mathbb{R}^n$  be Lipschitz with constant  $K$ , and set  $M = \sup_{y \in B_p} |F(y)|$ . If  $a > 0$  is such that  $a < \min \left\{ \frac{1}{M}, \frac{1}{K} \right\}$ , then there exists a unique function  $x \in X$  that satisfies IVP.

Proof First, prove that for any  $x \in X$ , the following two conditions are equivalent

$$(I\text{VP}) \quad \dot{x} = F(x) \text{ and } x(t_0) = x_0$$

$$(I\text{E}) \quad x(t) = x_0 + \int_{t_0}^t F(x(s)) ds,$$

in which (I\text{VP}) stands for "initial-value problem" and (I\text{E}) stands for "integral equation". (In (I\text{VP}), it is tacitly assumed that the differentiability of  $x$  is part of the condition.) Details are left as an exercise.

We will prove that (IE) admits one and only one solution  $x \in X$ .

Defn: A function  $\mathcal{F}: X \rightarrow X$  is a contraction if  $\exists r \in \mathbb{R}$  such that  $0 < r < 1$  so that  $\forall x_1, x_2 \in X$ , one has

$$\|\mathcal{F}x_1 - \mathcal{F}x_2\| \leq r \|x_1 - x_2\|.$$

We will prove now that the map

$$(\mathcal{F}x)(t) := x_0 + \int_{t_0}^t F(x(s)) ds \quad (t \in J_a)$$

defines a contraction on  $X$ : Given a continuous function  $x: J_a \rightarrow B_f$ ,  $F \circ x: J_a \rightarrow \mathbb{R}^n$  is also continuous so that  $(\mathcal{F}x)(t)$  is well defined and

$$|\mathcal{F}x(t) - x_0| \leq \int_{t_0}^t |F(x(s))| ds \leq aM < \rho$$

so that  $\mathcal{F}x \in X$ . ( $\mathcal{F}x$  is continuous because  $\int_{t_0}^t F(x(s)) ds$  is.)

For  $x_1, x_2 \in X$ ,

$$(\mathcal{F}x_1 - \mathcal{F}x_2)(t) = \int_{t_0}^t [F(x_1(s)) - F(x_2(s))] ds,$$

and thus, by the Lipschitz property of  $F$ ,  $\forall t \in J_0$ ,

$$\begin{aligned} |(\mathcal{F}x_1 - \mathcal{F}x_2)(t)| &\leq \int_{t_0}^t |F(x_1(s)) - F(x_2(s))| ds \\ &\leq \int_{t_0}^t K |x_1(s) - x_2(s)| ds \leq aK \|x_1 - x_2\|_{\text{sup}} \end{aligned}$$

and thus  $\|\mathcal{F}x_1 - \mathcal{F}x_2\|_{\text{sup}} \leq aK \|x_1 - x_2\|_{\text{sup}}$  ~~with  $aK < 1$~~

Since  $aK < 1$ ,  $\mathcal{F}$  is a contraction in  $X$ .

4

Notice also that  $\forall x \in X$ ,  $(\mathcal{F}x)(t_0) = x_0$ .

Now we see that (IUP) and (IE) are equivalent to

(FP)  $\mathcal{F}: X \rightarrow X$  admits a unique fixed point.

Indeed, (IE) is exactly the statement that  $\mathcal{F}x = x$ .

To prove existence, choose  $y_0 \in X$  with  $y_0(t_0) = x_0$  and define recursively  $y_{n+1} = \mathcal{F}y_n$  for  $n \geq 1$ ,

[that is,  $y_n(t) = x_0 + \int_{t_0}^t F(y_{n-1}(s)) ds$ ].

Inductively, one proves by the contraction property of  $\mathcal{F}$ , that

$$\|y_{n+1} - y_n\|_{\text{sup}} \leq (ak)^n \|y_1 - y_0\|_{\text{sup}}.$$

Since  $ak < 1$ , the exponential convergence of  $\|y_{n+1} - y_n\|_{\text{sup}}$  to zero makes  $\{y_n\}_{n=0}^{\infty}$  a Cauchy sequence in  $X$ .

Since  $X$  is complete, this sequence admits a limit ~~point~~ function  $x \in X$ , and it is a fixed point of  $\mathcal{F}$  because

$$\mathcal{F}x = \mathcal{F} \lim_{n \rightarrow \infty} y_n = \lim_{n \rightarrow \infty} \mathcal{F}y_n = \lim_{n \rightarrow \infty} y_{n+1} = x.$$

A contraction has but a unique fixed point because if  $\mathcal{F}x_1 = x_1$  and  $\mathcal{F}x_2 = x_2$ , then

$$\|x_1 - x_2\| = \|\mathcal{F}x_1 - \mathcal{F}x_2\| \leq ak \|x_1 - x_2\|,$$

and since  $ak < 1$ , one has  $\|x_1 - x_2\| = 0$ , or  $x_1 = x_2$ . ▣

4

Some consequences of the existence/uniqueness theorem:

- Given a solution  $x: t_0 + (-a, a) \rightarrow B_p$  with  $x(t_0) = x_0$ , the function  $y: t_1 + (-a, a) \rightarrow B_p$  defined by

$$y(t) = x(t + t_0 - t_1)$$

satisfies  $\dot{y} = F(y)$ ,  $y(t_1) = x_0$ .

We say that the system is time-shift-invariant, and it is called "autonomous". This comes from the fact that  $F$  is a function of  $x$  and not  $t$ .

- Solutions can't cross:

If  $\dot{x} = F(x)$  and  $\dot{y} = F(y)$  and  $x(t_0) = x_0 = y(t_1)$ , then  $y(t_1 + s) = x(t_0 + s)$  on the maximal  $s$ -interval on which both are defined.

- Periodic solutions:

If  $x: (a, b) \rightarrow B_p$  is a solution to  $\dot{x} = F(x)$  and  $x(t_0) = x(t_0 + p)$  for some  $t_0 \in (a, b)$  and  $p$  such that  $t_0 + p \in (a, b)$ , then  $x$  can be extended uniquely to a periodic function

$x: \mathbb{R} \rightarrow B_p$  that satisfies  $\dot{x} = F(x)$  and

$x(t + p) = x(t)$  for all  $t \in \mathbb{R}$ . [You can do the details.]

## Exercise Nonautonomous systems.

Let  $F: t_0 + (-b, b) \times B_\rho \rightarrow \mathbb{R}^n$  be Lipschitz continuous with constant  $K$ , and let  $F$  be bounded by  $M$ .

Then there is an interval  $t_0 + (-a, a)$  such that the IVP

$$\begin{cases} \dot{x} = F(t, x) \\ x(t_0) = x_0 \end{cases}$$

admits a unique solution  $x: t_0 + (-a, a) \rightarrow B_\rho$ .

You can ~~do~~<sup>prove</sup> this by applying the theorem for autonomous systems to the extended autonomous system

$$\begin{cases} \dot{x} = F(x, t) \\ \dot{t} = 1 \end{cases}.$$

To show that  $a < \min \left\{ \frac{1}{K}, \frac{1}{M}, b \right\}$  works, you have to do just a little bit more than directly applying the theorem.



### Lemma (Gronwall's inequality)

Let  $f: [0, \alpha] \rightarrow \mathbb{R}$  be a continuous function with non-negative values, and let  $C, K \geq 0$  be such that

$$f(t) \leq C + \int_0^t K f(s) ds \quad \forall t \in [0, \alpha].$$

Then  $f(t) \leq Ce^{Kt}$ .

Proof For  $C > 0$ ; set  $g(t) := C + \int_0^t K f(s) ds$ .

Then  $g'(t) = K f(t)$ , so that  $\frac{g'(t)}{g(t)} \leq K$ .

Thus  $\ln g(t) = \ln g(0) + \int_0^t \frac{d}{ds} \ln g(s) ds \leq \ln C + Kt$

and so  $g(t) \leq Ce^{Kt}$ , and  $\therefore f(t) \leq Ce^{Kt}$ .

For  $C = 0$ , one has  $f(t) \leq C + \int_0^t K f(s) ds \quad \forall C > 0$ ,

and thus  $f(t) \leq Ce^{Kt} \quad \forall C > 0$ . This implies

$$f(t) \leq 0e^{Kt} \quad \blacksquare$$

### Theorem (Continuous dependence on initial conditions)

Let  $x_1$  and  $x_2$  be solutions to ~~the~~ the ODE  $\dot{x} = F(x)$  on the interval  $(-a, a)^{+t_0}$ . ~~with initial conditions~~ Then

$$|x_1(t) - x_2(t)| \leq |x_1(t_0) - x_2(t_0)| e^{K|t-t_0|}$$

for all  $t \in (-a, a)^{+t_0}$ , where  $K$  is the Lipschitz const. for  $F$ .

9

Proof Apply Gronwall's inequality to  $|x_1(t) - x_2(t)|$  :

$$x_1(t) = x_1(t_0) + \int_{t_0}^t F(x_1(s)) ds$$

$$x_2(t) = x_2(t_0) + \int_{t_0}^t F(x_2(s)) ds$$

$$\Rightarrow |x_1(t) - x_2(t)| = |x_1(t_0) - x_2(t_0)| \pm \int_{t_0}^t |F(x_1(s)) - F(x_2(s))| ds$$

with the + sign if  $t \geq t_0$  and the minus sign if  $t \leq t_0$ . Since  $|F(x_1(s)) - F(x_2(s))| \leq K|x_1(s) - x_2(s)|$ ,

an application of Gronwall's inequality yields

$$|x_1(t) - x_2(t)| \leq |x_1(t_0) - x_2(t_0)| e^{K|t - t_0|} \quad \blacksquare$$

### Continuous dependence on parameters

Consider a system in  $\mathbb{R}^{n+k}$  : ~~in  $\mathbb{R}^n$~~

$$\dot{x}, \dot{y} = F(x, y)$$

$$x(t_0) = x_0$$

$$y(t_0) = y_0$$

that is specialized in that  $F(x, y) \in \mathbb{R}^n \subset \mathbb{R}^n \times \mathbb{R}^k$

Thus  $y = 0$  and the variable  $y$  can be viewed as a fixed parameter in the dynamical system, and

the system is equivalent to 
$$\begin{cases} \dot{x} = F(x, y_0) \\ x(t_0) = x_0 \end{cases}$$

If  $F(\cdot, y)$  is uniformly Lipschitz (same  $K$  for all  $y$  in some set), the theorem on continuous dependence on initial conditions becomes a theorem on continuous dependence on parameters.



Assume now that  $F$  is continuously differentiable.

The flow of the solution  $x$  as the initial condition is varied.

Let  $x(t, \xi)$  satisfy

$$\begin{cases} \dot{x}(t, \xi) = F(x(t, \xi)) \\ x(0, \xi) = x_0 + \xi \end{cases}$$

on a common  $t$ -interval for  $|\xi| < \varepsilon > 0$ , with  $x(t, \xi) \in B_c$   
 $(-a, a)$

Let  $u(t, \xi)$  satisfy the ODE IVP  $\leftarrow$  linear!

$D_{\xi}x$

$$\begin{cases} \dot{u}(t, \xi) = DF_{x(t,0)} u(t, \xi) \\ u(0, \xi) = \xi \end{cases}$$

on the same  $t$ -interval for  $|\xi| < \varepsilon$ , with  $u(t, \xi) \in B_c$

Define  $g(t, \xi) = |x(t, \xi) - x(t, 0) - u(t, \xi)|$ .

We will prove that

$$(*) \quad \frac{g(t, \xi)}{|\xi|} \rightarrow 0 \quad \text{as } \xi \rightarrow 0.$$

From the IVPs that  $x(t, \xi)$  and  $u(t, \xi)$  satisfy, we obtain

$$g(t, \xi) \leq \int_0^t |F(x(s, \xi)) - F(x(s, 0)) - DF_{x(s,0)} u(s, \xi)| ds.$$

By the differentiability of  $F$ , we have

$$F(x(s, \xi)) - F(x(s, 0)) = DF_{x(s,0)} (x(s, \xi) - x(s, 0)) + R(s, \xi) |x(s, \xi) - x(s, 0)|,$$

in which  $R(s, \xi) \rightarrow 0$  as  $x(s, \xi) - x(s, 0) \rightarrow 0$ .

In fact this convergence is uniform over  $s$  because  $DF$  is uniformly continuous on  $B_\rho$  (recall  $B_\rho$  is closed).

[ I leave it as an exercise to prove this. You should use the mean-value theorem applied to  $F(x(s, \xi)) - F(x(s, 0))$ , considered as the endpoint values of the argument of  $F$  along a line segment. ]

We have already seen from the theorem on continuous dependence on initial conditions, that

$$|x(s, \xi) - x(s, 0)| \leq |\xi| e^{K|s|} \leq |\xi| e^{aK}$$

Thus  $R(s, \xi) \rightarrow 0$  as  $\xi \rightarrow 0$ , uniformly in  $s$ .

Putting  $\tilde{R}(s, \xi) = R(s, \xi) e^{K|s|}$ , we obtain

$$g(t, \xi) \leq \int_0^t |DF_{x(s,0)}(x(s, \xi) - x(s, 0) - u(s, \xi))| ds + |\xi| \int_0^t |\tilde{R}(s, \xi)| ds$$

with  $\tilde{R}(s, \xi) \rightarrow 0$  as  $\xi \rightarrow 0$  uniformly in  $s$  so that

$$\int_0^t |\tilde{R}(s, \xi)| ds \rightarrow 0 \text{ as } \xi \rightarrow 0.$$

Let  $|DF_y| \leq N \forall y \in B_\rho$ . Then (since  $F$  is  $C^1$  on  $B_\rho$ )

$$g(t, \xi) \leq \int_0^t N g(s, \xi) ds + |\xi| \int_0^t |\tilde{R}(s, \xi)| ds$$

By Gronwall's inequality,  $g(t, \xi) \leq |\xi| \int_0^t |\tilde{R}(s, \xi)| ds e^{Nt}$ , so

$$\frac{g(t, \xi)}{|\xi|} \leq e^{Nt} \int_0^t |\tilde{R}(s, \xi)| ds \rightarrow 0 \text{ as } \xi \rightarrow 0.$$

Since the system  $(D_\xi x)$  is linear, the map

$$\xi \mapsto U(t, \xi)$$

is linear, and it is, by virtue of (x), equal to the derivative of the flow  $x(t, \xi)$ , as a function of  $\xi$ .

Notice that, if  $x_0$  is a fixed point for the DE  $\dot{x} = F(x)$ , then  $x(t, 0) \equiv x_0$  and the system  $(D_\xi x)$  is autonomous and linear, so

$$U(t, \xi) = \exp(t DF_{x_0}) \cdot \xi$$