

Linear homogeneous autonomous ODEs

$$\dot{x} = Ax \quad (x \in \mathbb{R}^n, A: \mathbb{R}^n \rightarrow \mathbb{R}^n \text{ linear})$$

Uniqueness Let $x_1(t)$ and $x_2(t)$ be solutions of $\dot{x} = Ax$ for all $t \in (a, b)$ such that $x_1(t_0) = x_2(t_0)$ for some $t_0 \in (a, b)$. Then $x_1(t) = x_2(t) \forall t \in (a, b)$.
[Note $a = -\infty$ or $b = \infty$ is allowed.]

Proof For $t \in (a, b)$, set $x(t) = x_1(t) - x_2(t)$, and define $x(a)$ and $x(b)$ by continuity. Then $\dot{x} = Ax$ and $x(t_0) = 0$. Let $t_1 = \max_{t \in [a, b]} \{x(t) = 0\}$. (This max exists since x is continuous and the set is non-empty.)
For all r and t such that $t_1 \leq r \leq t \leq b$, $x(r) = A \int_{t_1}^r x(s) ds$ and thus

$$|x(r)| \leq |A| |r - t_1| \max_{s \in [t_1, r]} |x(s)| \leq |A| |t - t_1| \max_{s \in [t_1, t]} |x(s)|$$

$$\Rightarrow \max_{r \in [t_1, t]} |x(r)| \leq |A| |t - t_1| \max_{s \in [t_1, t]} |x(s)|$$

$$\Rightarrow (1 - |A| |t - t_1|) \max_{s \in [t_1, t]} |x(s)| \leq 0$$

Thus if $|t - t_1| < |A|^{-1}$, then $\max_{s \in [t_1, t]} |x(s)| = 0$, and by definition of t_1 , we must have $t_1 = t$, and thus $t_1 = b$.

An analogous argument proves that $a = \min_{t \in [a, b]} \{x(t) = 0\}$.

We conclude that $x(t) = 0 \forall t \in [a, b]$, that is $x_1 = x_2$. ▀

Existence There exists a solution $x(t)$ to $\dot{x} = Ax, x(t_0) = x_0$ defined for all $t \in \mathbb{R}$.

$E =$ identity matrix \square

Proof The matrix IVP $\dot{X} = AX, X(0) = E$ has solution $X(t) = \exp(tA) := \sum_{n=0}^{\infty} \frac{1}{n!} t^n A^n$

Indeed, $\forall T$, this series converges uniformly and absolutely for $|t| \leq T$; and term-by-term differentiation yields $\frac{d}{dt} e^{tA} = A e^{tA}$.

The vector function $x(t) = e^{tA} x_0$ therefore satisfies $\dot{x} = Ax$ and $x(0) = E x_0 = x_0$. \blacksquare

Basic properties of e^{tA}

- $M e^A M^{-1} = e^{M A M^{-1}}$
- $AB = BA \implies e^{A+B} = e^A e^B$
- $\det e^A = e^{\text{tr} A} = e^{\sum_{i=1}^m \lambda_i} = \prod_{i=1}^m e^{\lambda_i}$ [λ_i are the eivals of A]
- Since $\det e^{tA} = e^{t \text{tr} A}$ and the flow for $\dot{x} = Ax$ is $\phi_t(x) = e^{tA} x$, the flow scales volumes exponentially with rate $\text{tr} A$. Volume is preserved by the flow if and only if $\text{tr} A = 0$.

Behavior of e^{tA} : normal forms

Suppose that $AM = MA$. [If A is diagonalizable, Λ could be a diagonal matrix of eigenvalues of A and M the matrix whose columns are the eigenvectors.] Then for $\dot{x} = Ax$,

$$\phi_t(x) = e^{tA} x = e^{tM\Lambda M^{-1}} x = M e^{t\Lambda} M^{-1} x$$

Note that $M^{-1}x$ is the vector of components of x in the basis given by the columns of M .

So we should find $e^{t\Lambda}$ for all normal forms of matrices. Normal forms have canonical blocks :

$$A = \sum_{j=1}^N \lambda_j P_j, \quad E = \sum_{j=1}^N P_j, \quad P_j^2 = P_j$$

The second two say that the P_j are complementary projections. The λ_j are the canonical matrices

If we allow complex solutions to e^{tA} , all the λ_j are of Jordan form:

$$\lambda = \lambda E_m + N_m = \begin{bmatrix} \lambda & 1 & 0 & \dots & 0 \\ 0 & \lambda & 1 & & \\ & & \ddots & \ddots & \\ & & & \lambda & 1 \\ 0 & \dots & 0 & & \lambda \end{bmatrix}$$

where E_m is the $m \times m$ identity matrix and N_m is

the nilpotent matrix $N_m = \left(\delta_{i+1,j} \right)_{i,j=1}^m$.

Since E_m and N_m commute, $e^{t\lambda} = e^{t\lambda E_m} e^{tN_m}$.

We have $e^{t\lambda E_m} = e^{t\lambda} E_m$ and

$$e^{tN_m} = E_m + tN_m + \frac{t^2}{2} N_m^2 + \dots + \frac{t^{(m-1)}}{(m-1)!} N_m^{m-1}$$

because $N_m^m = 0$. Note that the operation $B \mapsto BN_m$ shifts the columns of B to the right (and the rightmost column of B disappears). Thus

Columns are the "modes" of the system.

$$e^{t\lambda} = e^{t\lambda} \begin{bmatrix} 1 & t & \frac{t^2}{2} & \dots & \frac{t^{m-1}}{(m-1)!} \\ 0 & 1 & t & \dots & \vdots \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & \dots & 1 \end{bmatrix}$$

$\lambda = a + bi$

Now suppose that A is real and that we are interested ultimately in the real solutions. Let $\lambda, \bar{\lambda}$ be a conjugate pair of eigenvalues of algebraic multiplicity 1. There is a basis of real vectors $\{v_1, v_2\}$ for the two-dim'l span of the eigenspaces of $a \pm bi$ together, and respect to which A acts like the rotation-dilation matrix

$$A \sim \begin{bmatrix} a & -b \\ b & a \end{bmatrix} \quad \text{on span } \{v_1, v_2\};$$

more precisely,

$$A[v_1, v_2] = [v_1, v_2] \begin{bmatrix} a & -b \\ b & a \end{bmatrix}.$$

This normal form can be decomposed as

$$C = \begin{bmatrix} a & -b \\ b & a \end{bmatrix} = aE + bJ,$$

with $J = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$. Notice that $J^2 = -E$.

Using this, you can compute that e^{bJ} is a rotation matrix:

$$e^{bJ} = \begin{bmatrix} \cos b & -\sin b \\ \sin b & \cos b \end{bmatrix} =: R(b)$$

Since E and J commute,

$$e^{tC} = e^{taE} e^{tbJ} = e^{ta} R(tb).$$

Thus the flow of $\dot{x} = Ax$ within $\text{span}\{v_1, v_2\}$ is a combination of exponential and rotational behavior.

If λ has higher multiplicity, then the real normal form of A has Jordan-type blocks of the form

$$\Lambda = E \otimes C + N \otimes E = \begin{bmatrix} a-b & 1 & 0 & \dots & 0 & 0 \\ b & a & 0 & 1 & \dots & 0 & 0 \\ 0 & 0 & a-b & 1 & 0 & \dots & 0 \\ 0 & 0 & b & a & 0 & 1 & \dots \\ \vdots & & & & & & \ddots \\ 0 & 0 & \dots & 0 & 0 & a-b & 1 \\ 0 & 0 & \dots & 0 & 0 & b & a \end{bmatrix} = \begin{bmatrix} C & E & 0 & \dots & 0 \\ 0 & \dots & \dots & \dots & 0 \\ \vdots & & & & \vdots \\ 0 & \dots & 0 & C \end{bmatrix}$$

acting in $\mathbb{R}^m \otimes \mathbb{R}^2$, and

$$e^{t\Lambda} = e^{ta} \begin{bmatrix} R(tb) & tR(tb) & \dots & \frac{t^{m-1}}{(m-1)!} R(tb) \\ 0 & R(tb) & \dots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & R(tb) \end{bmatrix}$$